Mathematical Case Studies:

Some Topology*

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Abstract

This ProofPower-HOL document contains definitions and proofs concerning some basics of abstract topology, metric space theory and algebraic topology (more precisely, elementary homotopy theory). It presents the material using the approach taken in [1]: the main body of the document contains the definitions together with a narrative commentary including a discussion of the theorems that have been proved. This is followed by a listing of the theory and an index to the theorems and definitions. The source text of this document also contains the proof scripts, but these are suppressed from the printed form by default.

The coverage of abstract topology includes the definitions of the following: topologies; construction of new topologies from old as (binary) product spaces or subspaces; continuity, Hausdorff spaces; connectedness; compactness, the interior, boundary and closure operators; a notion of protocomplex that we later use to define CW complexes. A range of basic theorems are proved, including: continuity of functional composition and of the structural maps for products; preservation of compactness and connectedness under continuous maps; connectedness resp. compactness of products of connected resp. compact spaces.

The coverage of metric spaces is very minimal. The standard arguments in the algebraic topology we are interested in can be done with almost no metric space ideas. The main idea that is needed is the notion of the Lebesgue number of a covering (which is needed to show that if you cover an interval or a square with open sets, then on some suitably fine subdivision of the interval or square, each subinterval or grid cell is contained in one of the covering sets). With these applications in view, the metrics for the real line and the plane are defined. We also define euclidean n-space in general using lists of reals for the representation and use these to define cubes, spheres and CW complexes. (Technical note: we actually use the L_1 (Manhattan taxi-cab) metric on product spaces, not the more usual L_2 (Euclidean) metric. The L_1 metric gives the same topology and makes the arithmetic easier in most cases.)

Finally, we deal with some basics of homotopy theory. This material is very far from complete. Currently we have: the definition of path connectedness and the proof that path connected spaces are connected; definitions of the notions of homotopy and of homotopy classes with the proofs that the homotopy relation is an equivalence relation; definitions of the path space (qua set, not qua space, in fact) together with the of the operations that induce a groupoid structure on the homotopy classes in the path space together with the proofs that these operations do indeed give a groupoid modulo homotopy equivalence; definition of the fundamental group and the proof that it is a group; definition of a covering projection and a proof that covering projections enjoy the unique lifting property and the homotopy lifting property.

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Acknowledgments

Thanks to Bill Richter for pointing out that one can define the notion of homotopy lifting property with respect to a given space without falling foul of the restriction on type variables in constant specifications.

References

[1] LEMMA1/HOL/WRK066. Mathematical Case Studies: Basic Analysis. R.D. Arthan, Lemma 1 Ltd., rda@lemma-one.com.

1 ABSTRACT TOPOLOGY

1.1 Technical Prelude

The following ML commands set up a theory "topology" to hold the definitions and theorems and set up a convenient proof context. The parents of the theory are the theory "bin_rel" of binary relations and the theory "fincomb" of finite combinatorics.

```
| force_delete_theory "topology" handle Fail _ => (); | open_theory "bin_rel"; | set_merge_pcs["basic_hol1", "'sets_alg"]; | new_theory "topology"; | new_parent"fincomb";
```

1.2 Topologies

We begin with the definition of a topology. We follow the most common tradition of defining a topology by specifying its set of open sets. The polymorphic set *Topology* is the set of all sets of sets that we will consider to be topologies. We do not require a topology to form a topology on the universe of the type of its points. For example, we wish to consider sets such as the unit interval in the real line to be topological spaces in their own right. This actually simplifies the definition: we just require a topology to be a set of sets that is closed under arbitrary unions and binary intersections. We do not require the carrier set of the topology to be a non-empty set (as some elementary text books do, unnecessarily). Nor do we need to make a special case of the empty set — it will be shown to be an open set in any topology (as the union of an empty set of open sets).

SML

```
HOL Constant
```

```
Topology: 'a SET SET SET
Topology = \{\tau \mid (\forall V \bullet V \subseteq \tau \Rightarrow \bigcup V \in \tau) \land (\forall A B \bullet A \in \tau \land B \in \tau \Rightarrow A \cap B \in \tau)\}
```

We can recover the carrier set of a topology as the union of all its open sets. It reads quite nicely to call this the *space* of the topology.

SML

HOL Constant

A set is *closed* with respect to a topology, τ , if it is the complement of an open set (i.e., a member of τ) relative to the space of τ . For this and several other concepts, we use postfix notation to suggest informal notations like " τ -closed".

```
SML |declare\_postfix(400, "Closed");

HOL Constant | $Closed: 'a \ SET \ SET \ \to 'a \ SET \ SET
```

 $\forall \tau \bullet \tau \ Closed = \{ A \mid \exists B \bullet B \in \tau \land A = Space_T \ \tau \setminus B \}$

Note that in the above definition and in those that follow, we do no stipulate that τ actually be a topology. We will agree, however, in stating theorems, to make that an assumption whenever necessary (which is nearly always in theorems of any interest).

The theorems begin with some preliminary lemmas about enumerated sets, finite sets and maxima and minima that belong elsewhere eventually.

Now comes a batch of useful basic facts about open and closed sets: the empty set and the space of a topology are both open and both closed; a set is open iff it contains an open neighbourhood of each of its points; a set is closed iff its complement contains an open neighbourhood of each of its points; any member of an open set is a member of the space (a technical convenience in later proofs); binary unions and, more generally, arbitrary unions of open sets are open; binary intersections and, more generally, finite intersections of open sets are open.

```
\begin{array}{lll} empty\_open\_thm & \in\_space\_t\_thm \\ space\_t\_open\_thm & \cup\_open\_thm \\ empty\_closed\_thm & \bigcup\_open\_thm \\ space\_t\_closed\_thm & \cap\_open\_thm \\ open\_open\_open\_neighbourhood\_thm & finite\_\bigcap\_open\_thm \\ closed\_open\_neighbourhood\_thm & \end{array}
```

1.3 New Topologies from Old: Subspace and Product Topologies

We borrow the Z symbol for range restriction (decorated with a subscript to avoid overloading) for the operator that forms the subspace of a topological space defined by some subset of the universe of its points. If that subset contains points outside the carrier set of the topological space they are ignored. A set is open with respect to the subspace topology defined by a subset X of the space of the topology iff it is the intersection of an open set with X.

```
SML |declare\_infix(280, "\lhd_T");
```

HOL Constant

$$\begin{vmatrix} \$ \lhd_{T} : 'a \ SET \rightarrow 'a \ SET \ SET \\ \hline \\ | \forall X \ \tau \bullet \qquad (X \lhd_{T} \tau) \\ | = \{A \mid \exists B \bullet \ B \in \tau \land A = B \cap X\}$$

We now give basic facts about the subspace topology induced by a subset of the space of a topology: it is a topology; its space is the subset; if the subset is the space of the topology, the subspace topology and the original are the same.

 $subspace_topology_thm$ $subspace_topology_space_t_thm$ $trivial_subspace_topology_thm$

The definition of the (binary) product topology is the usual one (which amounts to saying that the sets of the form $A \times B$ where A and B are open in the factors of the product provide a basis for the product topology).

SML

 $|declare_infix(290, "\times_T");$

HOL Constant

$$\$ \times_{T} : 'a \ SET \ SET \to 'b \ SET \ SET \to ('a \times 'b) \ SET \ SET$$

$$\forall \sigma \ \tau \bullet (\sigma \times_{T} \tau) = \{ C \mid \forall \ x \ y \bullet (x, y) \in C$$

$$\Rightarrow \exists A \ B \bullet \ A \in \sigma \land B \in \tau \land x \in A \land y \in B \land (A \times B) \subseteq C \}$$

The product topology is indeed a product topology and the space of the product topology is the product of the spaces of the factors:

 $product_topology_thm$

product_topology_space_t_thm

The trivial topology on a 1-point type is useful.

HOL Constant

$$\$1_T: ONE\ SET\ SET$$

$$1_T = \{\{\};\ \{One\}\}$$

 $unit_topology_thm$

 $unit_topology_space_t_thm$

Now we define the *n*-th power topology for finite *n*: if the space of τ is $X \Pi_T n \tau$ is the usual topology on X^n .

HOL Constant

```
 \begin{array}{|c|c|c|c|} \$\Pi_T : \mathbb{N} \to 'a \; SET \; SET \to 'a \; LIST \; SET \; SET \\ \hline \\ \forall \tau \; n \bullet & \Pi_T \; 0 \; \tau = \{ \; \{ \}; \; \{ [] \} \; \} \\ \land & (\Pi_T \; (n+1) \; \tau) = \{ C \; | \; \neg [] \in C \land \forall \; x \; v \bullet \; Cons \; x \; v \in C \Rightarrow \\ \hline \\ \exists A \; B \bullet \; A \in \tau \land B \in \Pi_T \; n \; \tau \land x \in A \land v \in B \land \\ \hline \\ \forall y \; w \bullet y \in A \land w \in B \Rightarrow Cons \; y \; w \in C \} \\ \hline \end{array}
```

Apart from the easy lemma which says that the lists in Π_T n τ are all of length n and the fact that the power topology is a topology, we defer proofs about the power topology until we have defined homeomorphisms.

 $power_topology_length_thm$

power_topology_thm

1.4 Continuity

There are some issues about the precise formalisation of continuity. The interesting part is completely standard: a function is continuous iff the inverse images of open sets are open sets. Clearly, there are two topologies here: one for the domain of the function and one for its range. It is technically convenient to work with functions that are total on the universe of the type of the domain. In any case, we want to support something like the usual way of thinking in the calculus where one doesn't carefully restrict every function to the domain of interest. E.g., one says things like "1/sin x is continuous from $(0, \pi/2)$ to the positive real numbers.".

The upshot is the following definition of a continuous function from the topological space σ to the topological space τ . The function is required to map the carrier set of σ to that of τ . It may well also map things outside the carrier set of σ into that of τ , and these need to be filtered out when we are testing whether the inverse image of an open set is open.

```
SML
```

```
declare_postfix(400, "Continuous");
```

HOL Constant

We now give some principles for recognising continuous functions. First of all a function is continuous iff the inverse image of each closed set is closed. The restriction of a continuous function to a subspace is continuous. The following are all continuous: constant functions, identity functions, compositions of continuous functions, the projections of a product onto its factors, the pointwise product of two continuous functions with common domain, the natural injections of a factor of a product into the product, the inclusion of the diagonal into the product of a topological space with itself, a function whose domain or range is the unit topological space, and, finally, a function defined by cases under

suitable hypotheses. The last-mentioned principle says that, given two continuous functions, f and g, on the same topological space and a subset, X, of their domain, the function that agrees with f on X and with g elsewhere is continuous provided f and g agree on each point which lies both in the closure of X and in the closure of its complement.

 $continuous_closed_thm$ $subspace_continuous_thm$ $const_continuous_thm$ $id_continuous_thm$ $comp_continuous_thm$ $left_proj_continuous_thm$ $right_proj_continuous_thm$ $product_continuous_thm$ $product_continuous_thm$ $product_continuous_\Leftrightarrow_thm$

left_product_inj_continuous_thm
right_product_inj_continuous_thm
domain_unit_topology_continuous_thm
range_unit_topology_continuous_thm
diag_inj_continuous_thm
cond_continuous_thm

1.5 Hausforff Separation Condition

Now we define the Hausdorff separation condition. A topology is Hausdorff iff any two distinct elements possess disjoint open neighbourhoods.

SML

HOL Constant

```
Hausdorff: 'a \ SET \ SET \ SET
Hausdorff = \{\tau \mid \forall x \ y \bullet \ x \in Space_T \ \tau \land y \in Space_T \ \tau \land \neg x = y \}
\Rightarrow \exists A \ B \bullet A \in \tau \land B \in \tau \land x \in A \land y \in B \land A \cap B = \{\}\}
```

A subspace of a Hausdorff space is Hausdorff as is the product of two Hausdorff spaces:

 $subspace_topology_hausdorff_thm$

 $product_topology_hausdorff_thm$

1.6 Compactness

The definition of compactness is the standard one (a topology is compact iff every open covering has a finite subcovering), together with the explicit requirement that the compact set be a subset of the space of the topology in question.

```
SML | declare_postfix(400, "Compact");
```

HOL Constant

Compactness is a topological property, i.e., compactness of a set depends only on the topology induced on the set and not on how the set is embedded in the containing topological space; continuous functions map compact sets to compact sets; the union of two compact sets is again compact; a compact subset of a Hausdorff space is closed. The final result is preceded by a simple lemma about separating a point from the union of a finite set of sets.

```
compact\_topological\_thm image\_compact\_thm \cup\_compact\_thm
```

 $compact_closed_lemma$ $compact_closed_thm$

Now we show that the product of two compact sets is compact. This is the finite case of Tychonov's theorem. The proof in the finite case is much simpler than the general case. Moreover the general case is probably best stated in terms of a topology on a function space and we do not wish to consider such topologies yet. We sneak up on the proof in three steps: the first two are of general use: $compact_basis_thm$ says that given a basis for a topology, to check compactness of a set one only needs to consider coverings by basic open sets and $compact_basis_product_topology_thm$ is the special case of this where the topology is the product topology and the basis is the basis that defines the product topology. $compact_product_lemma$ is a somewhat ad hoc lemma that is needed in the proof of the main theorem and might be of use elsewhere.

```
compact\_basis\_thm compact\_product\_lemma compact\_basis\_product\_topology\_thm product\_compact\_thm
```

Finally, for use in producing Lebesgue numbers of coverings of compact subsets of metric spaces, we prove that compact sets are sequentially compact (every countable subset has a limit point). We precede the proof by a lemma saying that if a (countably infinite) sequence ranges over the union of a finite family of sets, then some member of the family is visited infinitely often.

 $compact_sequentially_compact_lemma$ $compact_sequentially_compact_thm$

1.7 Connectedness

Similarly, the definition of connectedness is the standard one (a topology is connected if its space cannot be written as the union of two disjoint open sets), again together with the explicit requirement that the connected set be a subset of the carrier set of the topology in question.

```
|declare\_postfix(400, "Connected");
```

HOL Constant

Connectedness is a topological property¹. a set is connected iff it cannot be separated by two closed sets; a set is connected iff any two of its points are contained in a connected subset of the set (which doesn't sound very useful, but is, so much so that we present it both as a conditional rewrite rule and in a form suitable for back-chaining);

```
\begin{array}{cccc} connected\_topological\_thm & connected\_pointwise\_thm \\ connected\_closed\_thm & connected\_pointwise\_bc\_thm \end{array}
```

The empty set is connected as is any singleton set; continuous functions map connected sets to connected sets; the union of two non-disjoint connected sets is connected as is the product of any two connected sets. If the union of two non-empty open (or closed) sets is connected the two sets cannot be disjoint.

Results of the following sort capture common ways of thinking about spaces such as geometric simplicial complexes or CW complexes constructed by gluing together connected pieces:

- the union of three connected sets is connected if they can be listed, so that each member meets the next member in the list:
- if a connected set is covered by a set of connected sets, then the union of the covering sets is itself connected;
- if the union of two connected sets is not connected, then the two sets can be separated (by two open sets, which may not be disjoint in general, but are each disjoint from the union);
- if a connected set can be separated from each of a finite family of connected sets, then it can be separated from the union of the family;
- given a finite family of non-empty connected sets U and a connected set B such that B is connected as is the union of B and the sets in U, if B does not contain every set in U, then there is some set A in U such that the union of A and B is connected;
- given a finite family of non-empty connected sets U and a member A of U, one can begin with A and deal out sets from U such that at each stage the union of the sets that have been dealt

¹The use of $A \cap B \cap C = \{\}$ rather than $B \cap C = \{\}$ in the definition is perhaps surprising, but connectedness would not be a topological property with the latter formulation. To see this, consider a space X with three points x, y and z, topologised so that O is open iff $O = \{\}$ or $z \in O$. Then x and y cannot be separated by disjoint open sets in X, but $\{x,y\}$ is not connected under the subspace topology.

is connected, such that each set dealt adds to this union whenever that is possible, and such that eventually the union of the sets that have been dealt is equal to the union of all the sets in U:

• given a finite family of non-empty connected sets U and a member A of U, either A contains the union of all the sets in U, or there is a B in U not equal to A and such that the union of the sets in U other than B is connected and does not contain B.

U_U_connected_thm cover_connected_thm separation_thm finite_separation_thm $connected_extension_thm$ $connected_chain_thm$ $connected_step_thm$

1.8 Homeomorphisms

A homeomorphism is a continuous mapping with a continuous two-sided inverse:

SML

```
|declare\_postfix(400, "Homeomorphism");
```

HOL Constant

The identity function is a homeomorphism as is the composite of two homeomorphisms, the product of a pair of homeomorphisms, the natural mapping from a space and its product with a one-point space and the function on product that interchanges the factors; a homeomorphism is an open mapping (i.e., it sends open sets to open sets) and is also one-to-one; a function is a homeomorphism iff it is a one-to-one, onto, continuous open mapping. Finally, a useful principle for recognising homeomorphisms obtained by restricting continuous functions defined on compact Hausdorff spaces.

```
id\_homeomorphism\_thm comp\_homeomorphism\_thm product\_homeomorphism\_thm product\_unit\_homeomorphism\_thm swap\_homeomorphism\_thm
```

 $homeomorphism_open_mapping_thm$ $homeomorphism_one_one_thm$ $homeomorphism_onto_thm$ $homeomorphism_one_open_mapping_thm$ $\subseteq_compact_homeomorphism_thm$

The useful principle is this: Let C and X be Hausdorff spaces with C compact and let f be a continuous function from C to X. If $B \subseteq C$ is such that for every $y \in f(B)$ there is a unique x in C such that f(x) = y, then f restricts to a homeomorphism between B and f(B). To see this, note

that it is enough to prove that the restriction of f to B is a closed mapping, since evidently f is one-one and continuous on B. Given a closed subset A of B, we have $A = B \cap D$ where D is some closed and hence compact subset of C. By assumption $f(D \setminus B)$ is disjoint from f(B), which implies that $f(D \cap B) = f(D) \cap f(B)$. Since D is compact, so also is f(D), whence f(D) is closed. Thus $f(A) = f(D) \cap f(B)$ is a closed subset of f(B).

1.9 Interior, Boundary and Closure Operators

Our definitions of the interior, boundary and Closure operators are standard, but as we have to be explicit about the ambient topology, we take them to be infix operators, reflecting usages like "the τ -interior of A" that one might use when working with several different topologies on the same set.

```
declare_infix(400, "Interior");
declare_infix(400, "Boundary");
declare_infix(400, "Closure");
```

The τ -interior of A comprises the points that lie in τ -open subsets of A; the τ -boundary comprises the points (of the space) all of whose open neighbourhoods meet both A and its complement; the τ -closure of A is the smallest τ -closed set containing (the points of the space belonging to) A.

```
$Interior $Boundary $Closure: 'a SET SET \rightarrow 'a SET \rightarrow 'a SET

\forall \tau \ A \bullet
\tau \ Interior \ A = \{x \mid \exists B \bullet \ B \in \tau \land x \in B \land B \subseteq A\}
\land \tau \ Boundary \ A =
\{x \mid x \in Space_T \ \tau \land \forall B \bullet \ B \in \tau \land x \in B \Rightarrow \neg B \cap A = \{\} \land \neg B \setminus A = \{\}\}
\land \tau \ Closure \ A = \bigcap \{B \mid B \in \tau \ Closed \land A \cap Space_T \ \tau \subseteq B\}
```

The interior and boundary of a set are subsets of the ambient space and the interior is a subset of the set; the boundary of a set is the complement of the union of its interior and the complement of its interior; the interior of the product of two sets is the product of their interiors; a set is open iff it is disjoint from its boundary and closed iff it contains its boundary; the interior of a set is the union of its open subsets; the closure of a set is the complement of the interior of its complement.

```
\begin{array}{lll} interior\_boundary\_\subseteq\_space\_t\_thm & open\_\Leftrightarrow\_disjoint\_boundary\_thm \\ interior\_\subseteq\_thm & closed\_\Leftrightarrow\_boundary\subseteq\_thm \\ boundary\_interior\_thm & interior\_\bigcup\_thm \\ interior\_\times\_thm & closure\_interior\_complement\_thm \end{array}
```

1.10 The discrete topology

A topology is discrete if any subset of its space is open.

We prove that continuity is trivial for mappings on a space with the discrete topology, that a topology is discrete iff the singletons are open and that a mapping from a non-empty connected space to a discrete space has a singleton range.

```
discrete\_t\_continuous\_thm open\_singletons\_discrete\_thm connected\_continuous\_discrete\_thm
```

1.11 Covering Projections

Our definition of covering projection is completely standard: a continuous function is a covering projection if every point in its range has a neighbourhood C whose inverse image is a disjoint union of open sets each of which is mapped homeomorphically onto C.

```
SML
```

```
| declare_postfix(400, "CoveringProjection");
```

HOL Constant

We define the unique lifting property of a function p from a space σ to a space τ for functions from a space ρ .

```
 \begin{array}{|c|c|c|c|} \hline \textbf{UniqueLiftingProperty} : ('a \ SET \ SET \ \times (('b \rightarrow 'c) \times 'b \ SET \ SET \times 'c \ SET \ SET)) \ SET \\ \hline \\ \hline \\ \forall \rho \ \sigma \ \tau \ p \bullet \\ \hline \\ (\rho, \ (p, \ \sigma, \ \tau)) \in \textbf{UniqueLiftingProperty} \Leftrightarrow \\ \\ \forall f \ g : 'a \rightarrow 'b; \ a : 'a \bullet \\ \\ f \in (\rho, \ \sigma) \ Continuous \\ \\ \land \qquad g \in (\rho, \ \sigma) \ Continuous \\ \\ \land \qquad (\forall x \bullet \ x \in Space_T \ \rho \Rightarrow p(f \ x) = p(g \ x)) \\ \\ \land \qquad a \in Space_T \ \rho \\ \\ \land \qquad g \ a = f \ a \\ \\ \Rightarrow \qquad \forall x \bullet \ x \in Space_T \ \rho \Rightarrow g \ x = f \ x \\ \hline \end{array}
```

We prove two lemmas that fit together to give the unique lifting property for continuous functions from a connected space into the base space of a covering projection.

```
\begin{array}{ll} unique\_lifting\_lemma1 & unique\_lifting\_thm \\ unique\_lifting\_lemma2 & unique\_lifting\_bc\_thm \end{array}
```

1.12 Protocomplexes

In a later version of this document we intend to define the notion of a CW complex. To support this, it is convenient to define some purely topological notions. A protocomplex will comprise a set of pairs representing a partial function from certain closed subsets of a topological space X to the natural numbers. The sets in the domain of this function will be referred to as cells and the natural number associated with a cell will be called its dimension. Informally, we call a cell of dimension m an m-cell. The union of all the cells is the space of the protocomplex:

HOL Constant

```
Space_{K} : ('a \ SET \times \mathbb{N}) \ SET \to 'a \ SET
\forall C \bullet \ Space_{K} \ C = \bigcup \{c \mid \exists m \bullet \ (c, \ m) \in C\}
```

(We distinguish the name with a subscript K as in the German Komplex, since we use C elsewhere for the complex numbers.)

We define the n-skeleton of C to be the union of all cells of dimension at most n.

SML

```
|declare\_infix(400, "Skeleton");
```

HOL Constant

Our requirements on a protocomplex are as follows: (i) each cell is a closed set, (ii) for every x in X there is a unique m-cell c such that x lies in the interior of c with respect to the relative topology on the m-skeleton of C, (iii) a subset A of X is closed if $A \cap c$ is closed for every cell c, and (iv) each m-cell meets only finitely many cells of lower dimension.

```
Protocomplex: 'a SET SET → ('a SET × ℕ) SET SET

∀C τ • C ∈ Protocomplex τ ⇔ (∀c m • (c, m) ∈ C ⇒ c ∈ τ Closed)

∧ (∀x • x ∈ Space_K C ⇒ ∃₁ (c, m) • (c, m) ∈ C ∧ x ∈ ((m Skeleton C) ⊲_T τ) Interior c)

∧ (∀A • A ⊆ Space_K C ∧ (∀c m • (c, m) ∈ C ⇒ A ∩ c ∈ τ Closed) ⇒ A ∈ τ Closed)

∧ (∀c m • (c, m) ∈ C ⇒ {(d, n) | (d, n) ∈ C ∧ n < m ∧ ¬c ∩ d = {}} ∈ Finite)
```

2 METRIC SPACES — DEFINITIONS

In the following, we bring in the theory of analysis from [1], although we could make do just with the real numbers to start with.

SML

```
force\_delete\_theory "metric\_spaces" handle Fail \_ => (); \\ open\_theory "topology"; \\ new\_theory "metric\_spaces"; \\ new\_parent"analysis"; \\ new\_parent"trees"; \\ set\_merge\_pcs["basic\_hol1", "'sets\_alg", "'\noting", "'\noting"]; \\ \end{cases}
```

Our treatment of metric spaces is very minimal. The main fact we are interested in will be that coverings of compact subsets of metric spaces have a Lebesgue number. The definitions involved are the concept of a metric:

HOL Constant

 \dots and the concept of the metric topology, which we write as a postfix since otherwise the notation for concepts such as "compact with respect to the metric topology induced by D" look rather strange.

SML

```
|declare\_postfix(400, "MetricTopology");
```

HOL Constant

We prove some basic facts about the metric topology and about the sum metric on a product of metric spaces.

```
metric\_topology\_thm \\ space\_t\_metric\_topology\_thm \\ open\_ball\_open\_thm \\ open\_ball\_neighbourhood\_thm \\ \\ metric\_topology\_hausdorff\_thm \\ product\_metric\_thm \\ product\_metric\_topology\_thm \\ \\ open\_ball\_neighbourhood\_thm \\ \\
```

We prove the existence of Lebesgue numbers and that if X is a compact subset of an open space A in a metric space, then for small $\epsilon > 0$, A contains the ball $B(x, \epsilon)$ for every $x \in X$.

We also define an induced metric on the set of lists of elements of a metric space. We use this, for example, to define n-dimensional euclidean space. Getting a good definition is a little delicate: given a (non-empty) metric space A with metric d, fix an arbitrary element $a \in A$ and let A^* be the set of countably infinite sequences in A that take the constant value a for all but finitely many indices. A^* becomes a metric space under the metric d^* defined by $d^*(s,t) = \sum_i d(s_i,t_i)$. If we map lists to infinite sequences by padding with a, this induces a pseudo-metric on the space A^L of lists of elements of A. To get a metric, we take $d^L(v,w) = |\#v - \#w| + d^*(vaaa..., waaa...)$, where #v is the length of the list v.

HOL Constant

```
ListMetric: ('a \times 'a \rightarrow \mathbb{R}) \rightarrow ('a \ LIST \times 'a \ LIST) \rightarrow \mathbb{R}

∀D x v y w•

ListMetric D ([], []) = 0.

∧ ListMetric D (Cons x v, []) = 1. + D(x, Arbitrary) + ListMetric D (v, [])

∧ ListMetric D ([], Cons y w) = 1. + D(Arbitrary, y) + ListMetric D ([], w)

∧ ListMetric D (Cons x v, Cons y w) = D(x, y) + ListMetric D (v, w)
```

```
list_pseudo_metric_lemma1
list_pseudo_metric_lemma2
list_metric_nonneg_thm
```

 $list_metric_sym_thm$ $list_metric_metric_thm$

3 THE REAL LINE AND THE PLANE — DEFINITIONS

```
| force_delete_theory "topology_\mathbb{R}" handle Fail \( - => \) | open_theory "metric_spaces"; | new_theory "topology_\mathbb{R}"; | set_merge_pcs["basic_hol1", "'sets_alg", "'\mathbb{Z}", "'\mathbb{R}"];
```

We will make much use of the standard topology on the real line and so we define a short alias for it:

```
SML
```

```
|declare\_alias("O_R", \lceil Open_R \rceil);
```

We define the standard metric on the real line:

```
D_{R}: \mathbb{R} \times \mathbb{R} \to \mathbb{R}
\forall x \ y \bullet \ D_{R}(x, \ y) = Abs(y - x)
```

In the plane, as we are primarily interested in topological properties it is simple and convenient to use the L_1 -norm.

HOL Constant

We

```
\begin{array}{l} d_-\mathbb{R}\_2\_def1 \\ open_-\mathbb{R}\_topology\_thm \\ space\_t_-\mathbb{R}\_thm \\ closed\_closed_-\mathbb{R}\_thm \\ compact\_compact_-\mathbb{R}\_thm \\ continuous\_cts\_at_-\mathbb{R}\_thm \\ universe\_\mathbb{R}\_connected\_thm \\ closed\_interval\_connected\_thm \\ subspace_-\mathbb{R}\_thm \\ connected_-\mathbb{R}\_thm \\ \mathbb{R}\_\times_-\mathbb{R}\_topology\_thm \\ continuous_-\mathbb{R}\_\times_-\mathbb{R}\_\mathbb{R}\_thm \\ continuous_-\mathbb{R}_-\times_-\mathbb{R}\_\mathbb{R}\_thm \\ continuous_-\mathbb{R}_-\times_-\mathbb{R}\_\mathbb{R}\_thm \\ continuous_-\mathbb{R}_-\times_-\mathbb{R}\_\mathbb{R}\_thm \\ continuous_-\mathbb{R}_-\times_-\mathbb{R}\_\mathbb{R}\_thm \\ continuous_-\mathbb{R}_-\times_-\mathbb{R}\_\mathbb{R}\_thm \\ \end{array}
```

 $plus_continuous_R_\times_R_thm$ $times_continuous_R_\times Lthm$ $cond_continuous_R_thm$ $d_R_metric_thm$ $d_R_open_R_thm$ $d_R_2_metric_thm$ $d_R_2_open_R_\times_open_R_thm$ $open_R_hausdorff_thm$ $open_R_hausdorff_thm$ $R_lebesgue_number_thm$ $closed_interval_lebesgue_number_thm$ $product_interval_cover_thm$ $dissect_unit_interval_thm$ $product_interval_cover_thm$ $product_interval_cover_thm$

honour euclidean n-space with the name Space with no further decoration. For us, this is a family of topologies indexed by the natural numbers. The underlying spaces of the topologies comprise lists of real numbers.

```
SML
```

```
|declare\_postfix(400, "Space");
```

HOL Constant

```
\$Space: \mathbb{N} 
ightarrow \mathbb{R} \ LIST \ SET \ SET
orall n ullet n \ Space = \{v \mid \#v = n\} \lhd_T \ ListMetric \ D_R \ MetricTopology
```

The n-cube is the subpace of n-space comprising vectors with coordinates in the closed interval [0,1].

SML

```
declare\_postfix(400, "Cube");
```

```
\$Cube: \mathbb{N} \to \mathbb{R} \ LIST \ SET \ SET
\forall n \bullet \ n \ Cube = \{v \mid Elems \ v \subseteq ClosedInterval \ 0. \ 1.\} \vartriangleleft_T \ n \ Space
```

The open n-cube is the subpace of n-space comprising vectors with coordinates in the open interval (0,1).

```
SML
```

```
\left| \begin{array}{l} declare\_post fix (400, \ "OpenCube"); \\ \end{array} \right|
```

HOL Constant

```
\$ OpenCube: \mathbb{N} 
ightarrow \mathbb{R} LIST SET SET
```

```
\forall n \bullet n \ OpenCube = \{v \mid Elems \ v \subseteq OpenInterval \ 0. \ 1.\} \triangleleft_T \ n \ Space
```

The (topological) n-sphere is the subpace of the n-cube comprising vectors with at least one coordinate in the set $\{0,1\}$.

SML

```
declare\_postfix(400, \ "Sphere");
```

HOL Constant

```
\P 	binom{\$Sphere}: \mathbb{N} 	o \mathbb{R} 	ext{ \it LIST SET SET}
```

```
\forall n \bullet n \; Sphere = \{v \mid \neg Elems \; v \cap \{0.; 1.\} = \{\}\} \; \triangleleft_T \; n \; Cube
```

4 PATHS AND HOMOTOPY— DEFINITIONS

SML

```
| force_delete_theory "homotopy" handle Fail _ => ();
| open_theory "topology_R";
| new_theory "homotopy";
| new_parent "groups";
| set_merge_pcs["basic_hol1", "'sets_alg", "'Z", "'R"];
```

For convenience, we represent paths in a space as continuous functions on the whole real line. For the time being we do not define a topology on the path space (this was historically a slightly thorny topic in the literature and the "modern" solution via k-ification seems out of place at this stage).

HOL Constant

SML

```
Paths: 'a \ SET \ SET \rightarrow (\mathbb{R} \rightarrow 'a) \ SET
```

```
\forall \tau \bullet \quad Paths \ \tau = \\ \{ \qquad f \\ | \qquad f \in (O_R, \tau) \ Continuous \\ \land \qquad (\forall x \bullet \ x \leq 0. \Rightarrow f \ x = f \ 0.) \\ \land \qquad (\forall x \bullet \ 1. \leq x \Rightarrow f \ x = f \ 1.) \}
```

We now consider path connectedness. Here is the definition of a path connected set. $_{\mathrm{SML}}$

| declare_postfix(400, "PathConnected");

HOL Constant

 $PathConnected : 'a SET SET \rightarrow 'a SET SET$

SML

HOL Constant

```
LocallyPathConnected: 'a\ SET\ SET\ SET
```

```
\forall \tau \bullet \quad \tau \in LocallyPathConnected \\ \Leftrightarrow \quad \forall x \ A \bullet x \in A \land A \in \tau \Rightarrow \exists B \bullet B \in \tau \land x \in B \land B \subseteq A \land B \in \tau \ PathConnected
```

Continuing along the way towards the elements of algebraic topology, we now consider the notion of a homotopy. Here and elsewhere it is convenient to model functions continuous on the unit interval by functions continuous on the whole line. This is not problematic since any function continuous on the unit interval can be extended to be continuous everywhere.

Our homotopies are relative to a set X.

SML

 $|declare_postfix(400, "Homotopy");$

HOL Constant

\$Homotopy: 'a SET SET × 'a SET × 'b SET SET
$$\rightarrow$$
 ('a × $\mathbb{R} \rightarrow$ 'b) SET

$$\forall \sigma \ X \ \tau \bullet \ (\sigma, \ X, \ \tau) \ Homotopy = \{H \mid H \in ((\sigma \times_T \ O_R), \ \tau) \ Continuous \land \forall x \ s \ t \bullet x \in X \Rightarrow H(x, \ s) = H(x, \ t)\}$$

SML

 $|declare_postfix(400, "Homotopic");$

HOL Constant

 $\$ Homotopic: 'a \ SET \ SET \ \times 'a \ SET \ \times 'b \ SET \ SET \ \to ('a \to 'b) \to ('a \to 'b) \to BOOL$

```
\forall \sigma \ X \ \tau \ f \ g \bullet
((\sigma, \ X, \ \tau) \ Homotopic) \ f \ g \Leftrightarrow
\exists H \bullet \ H \in (\sigma, \ X, \ \tau) \ Homotopy
\land (\forall x \bullet \ H(x, \ \theta.) = f \ x) \land (\forall x \bullet \ H(x, \ 1.) = g \ x)
```

4.1 The Path Groupoid

Now we define addition of paths:

SML

 $|declare_infix(300, "+_P");$

HOL Constant

The identity elements of the path space may be taken to be the constant paths of zero length:

HOL Constant

$$\begin{array}{c} \mathbf{0}_{P} : 'a \to (\mathbb{R} \to 'a) \\ \\ \forall x \bullet \ \theta_{P} \ x = (\lambda t \bullet \ x) \end{array}$$

Now we define the inverse of a path:

SML

HOL Constant

$$\begin{array}{c}
\$ \sim_{\mathbf{P}} : (\mathbb{R} \to 'a) \to (\mathbb{R} \to 'a) \\
\hline
\forall f \bullet \sim_{P} f = (\lambda t \bullet f(1. - t))
\end{array}$$

It is convenient in later definitions and theorems to have a name for the homotopy relation for paths (namely homotopy with respect to the standard topology on the real line relative to the endpoints of the unit interval).

HOL Constant

We prove some basic facts about homotopies and paths.

 $path_connected_connected_thm$ $product_path_connected_thm$ $homotopic_refl_thm$ $homotopic_sym_thm$ $homotopic_trans_thm$ $homotopic_equiv_thm$ $homotopic_\subseteq thm$ $homotopic_\subseteq thm$ $homotopic_continuous_thm$ $homotopic_comp_left_thm$ $homotopic_comp_right_thm$ $homotopic_R_thm$ $paths_continuous_thm$

path_0_path_thm

path_plus_path_path_thm

minus_path_path_thm

path_plus_assoc_thm

path_plus_0_thm

path_0_plus_thm

path_plus_minus_thm

path_minus_minus_thm

path_minus_plus_thm

path_minus_plus_thm

path_rom_arc_thm

path_from_arc_thm

loop_from_arc_thm

We prove some facts about path connectedness and local path connectedness.

open_connected_path_connected_thm open_interval_path_connected_thm \mathbb{R} _locally_path_connected_thm product_locally_path_connected_thm

We define a standard retraction of the real line onto the unit interval. This is useful for constructing paths (following our conventions) from arbitrary continuous functions on the real line.

HOL Constant

```
| IotaI : \mathbb{R} \to \mathbb{R}
| IotaI = (\lambda x \bullet if \ x \le 0. \ then \ 0. \ else \ if \ x \le 1. \ then \ x \ else \ 1.)
```

We define the path lifting property for a continuous function p from a space σ to a space τ :

HOL Constant

$$\begin{array}{|c|c|c|c|} \hline \textit{PathLiftingProperty} : \\ & (('a \rightarrow 'b \) \times 'a \ SET \ SET \times 'b \ SET \ SET) \ SET \\ \hline \\ \hline \\ \forall \ \sigma \ \tau \ p \bullet \\ & (p, \ \sigma, \ \tau) \in \textit{PathLiftingProperty} \\ \Leftrightarrow & \forall f \ y \bullet \\ & f \in \textit{Paths} \ \tau \\ & \land \quad y \in \textit{Space}_T \ \sigma \\ & \land \quad p \ y = f \ 0. \\ & \Rightarrow \quad (\exists g \bullet \\ & \land \quad g \ 0. = y \\ & \land \quad (\forall s \bullet \ p(g \ s) = f \ s)) \\ \hline \end{array}$$

We define the notion of homotopy lifting property for a pair comprising a topological space ρ and a continuous mapping p from a topological σ to a topological space τ as follows:

```
x \in Space_T \ \rho
\wedge \qquad s \in ClosedInterval \ 0. \ 1.
\Rightarrow \qquad p(L(x, s)) = H(x, s)))
```

We prove that a covering project has the homotopy lifting property with respect to any space (i.e., it is a fibration) and hence also has the path lifting property.

covering_projection_fibration_thm

 $covering_projection_path_lifting_thm$

4.2 The Fundamental Group

We define a loop in a space τ with basepoint x to be a path that takes the value x everywhere outside the open interval (0,1).

HOL Constant

```
Loops: 'a SET SET \times 'a \rightarrow (\mathbb{R} \rightarrow 'a) SET

\forall \tau \ x \bullet \ Loops \ (\tau, \ x) = Paths \ \tau \cap \{f \mid \forall t \bullet \ t \leq 0. \ \lor \ 1. \leq t \Rightarrow f \ t = x\}
```

The following function maps a representative of an element of the fundamental group to the element it represents:

HOL Constant

The group multiplication in the fundamental group is defined by taking the path sum of representatives.

HOL Constant

```
FunGrpTimes: 'a SET SET × 'a \rightarrow (\mathbb{R} \rightarrow 'a) SET \rightarrow (\mathbb{R} \rightarrow 'a) SET \rightarrow (\mathbb{R} \rightarrow 'a) SET

\forall \tau \ x \ p \ q \ f \ g \bullet
\tau \in Topology \land x \in Space_T \ \tau \land
p \in Loops \ (\tau, x) \ / \ PathHomotopic \ \tau \land \ q \in Loops \ (\tau, x) \ / \ PathHomotopic \ \tau \land
f \in p \land g \in q \Rightarrow
FunGrpTimes(\tau, x) \ p \ q = FunGrpClass(\tau, x) \ (f +_P g)
```

The unit element in the fundamental group is the constant loop at the basepoint.

```
FunGrpUnit: 'a SET SET \times 'a \rightarrow (\mathbb{R} \rightarrow 'a) SET
\forall \tau \ x \bullet
FunGrpUnit(\tau, x) = FunGrpClass(\tau, x) (\theta_P x)
```

Then group inverse operation in the fundamental group is defined by taking the path negative of a representative.

HOL Constant

Putting the four components together gives us the fundamental group.

```
FunGrp: 'a SET SET \times 'a \rightarrow (\mathbb{R} \rightarrow 'a) SET GROUP

\forall \tau \ x \bullet
FunGrp(\tau, x) =
MkGROUP

(Loops \ (\tau, \ x) \ / \ PathHomotopic \ \tau)
(FunGrpTimes(\tau, \ x))
(FunGrpUnit(\tau, \ x))
(FunGrpInverse(\tau, \ x))
```

A THE THEORY topology

A.1 Parents

fincomb bin_rel

A.2 Children

 $metric_spaces$

A.3 Constants

 $egin{array}{ll} Topology & 'a & \mathbb{P} & \mathbb{P} & \mathbb{P} \\ Space_T & 'a & \mathbb{P} & \mathbb{P} & \rightarrow 'a & \mathbb{P} \\ \$Closed & 'a & \mathbb{P} & \mathbb{P} & \rightarrow 'a & \mathbb{P} & \mathbb{P} \end{array}$

 $^{\prime}a \mathbb{P} \mathbb{P} \rightarrow ^{\prime}b \mathbb{P} \mathbb{P} \rightarrow (^{\prime}a \leftrightarrow ^{\prime}b) \mathbb{P}$

 $\mathbf{1}_{T}$ ONE \mathbb{P} \mathbb{P}

 $\Pi_{T} \qquad \mathbb{N} \to 'a \mathbb{P} \mathbb{P} \to 'a LIST \mathbb{P} \mathbb{P}$ $\$Continuous \qquad 'a \mathbb{P} \mathbb{P} \times 'b \mathbb{P} \mathbb{P} \to ('a \to 'b) \mathbb{P}$

Hausdorff 'a \mathbb{P} \mathbb{P}

\$Homeomorphism

 $'a \mathbb{P} \mathbb{P} \times 'b \mathbb{P} \mathbb{P} \to ('a \to 'b) \mathbb{P}$

 $$Closure$ & 'a \mathbb{P} \mathbb{P} o 'a \mathbb{P} o 'a \mathbb{P} \\ $Boundary$ & 'a \mathbb{P} \mathbb{P} o 'a \mathbb{P} o 'a \mathbb{P} \\ $Interior$ & 'a \mathbb{P} \mathbb{P} o 'a \mathbb{P} o 'a \mathbb{P}$

 $'a \mathbb{P} \mathbb{P} \times 'b \mathbb{P} \mathbb{P} \to ('a \to 'b) \mathbb{P}$

UniqueLiftingProperty

 $'a \mathbb{P} \mathbb{P} \leftrightarrow (('b \rightarrow 'c) \times 'b \mathbb{P} \mathbb{P} \times 'c \mathbb{P} \mathbb{P})$

 $egin{array}{lll} Space_K & 'a \ \mathbb{P} \leftrightarrow \mathbb{N}
ightarrow 'a \ \mathbb{P} \ \$Skeleton & \mathbb{N}
ightarrow 'a \ \mathbb{P} \leftrightarrow \mathbb{N}
ightarrow 'a \ \mathbb{P} \ Protocomplex & 'a \ \mathbb{P} \ \mathbb{P}
ightarrow ('a \ \mathbb{P} \leftrightarrow \mathbb{N}) \ \mathbb{P} \end{array}$

A.4 Fixity

Right Infix 280:

 \lhd_T

Right Infix 290:

 \times_T

Right Infix 400:

 $Boundary \quad Closure \qquad Interior \qquad Skeleton$

Postfix 400: Closed Connected CoveringProjection

Compact Continuous Homeomorphism

A.5 Definitions

```
Topology
                               \vdash Topology
                                      = \{ \tau \}
                                      |(\forall \ V \bullet \ V \subseteq \tau \Rightarrow \bigcup \ V \in \tau)|
                                            \land (\forall A B \bullet A \in \tau \land B \in \tau \Rightarrow A \cap B \in \tau)\}
Space_T
                               \vdash \forall \ \tau \bullet \ Space_T \ \tau = \bigcup \ \tau
Closed
                               \vdash \forall \ \tau \bullet \ \tau \ Closed = \{A \mid \exists \ B \bullet \ B \in \tau \land A = Space_T \ \tau \setminus B\}
                               \vdash \forall \ X \ \tau \bullet \ X \ \lhd_T \ \tau = \{A | \exists \ B \bullet \ B \in \tau \land A = B \cap X\}
\lhd_T
                               \vdash \forall \sigma \tau
\times_T
                                   \bullet \sigma \times_T \tau
                                         = \{C
                                         |\forall x y
                                            \bullet (x, y) \in C
                                                  \Rightarrow (\exists A B)
                                                  • A \in \sigma
                                                        \land B \in \tau
                                                        \land x \in A
                                                        \land y \in B
                                                        \land (A \times B) \subseteq C)
1_T
                               \vdash 1_T = \{\{\}; \{One\}\}
\Pi_T
                               \vdash \ \forall \ \tau \ n
                                   • \Pi_T \ \theta \ \tau = \{\{\}; \{[]\}\}
                                         \wedge \Pi_T (n+1) \tau
                                            = \{C
                                            |\neg| \in C
                                                  \wedge (\forall x v)
                                                  • Cons \ x \ v \in C
                                                         \Rightarrow (\exists A B)
                                                         \bullet A \in \tau
                                                               \wedge \ B \in \varPi_{T} \ n \ \tau
                                                               \land x \in A
                                                               \land v \in B
                                                               \wedge (\forall y w)
                                                               • y \in A \land w \in B \Rightarrow Cons \ y \ w \in C)))
Continuous
                               \vdash \forall \sigma \tau
                                   • (\sigma, \tau) Continuous
                                         = \{f
                                         |(\forall x \bullet x \in Space_T \sigma \Rightarrow f x \in Space_T \tau)|
                                               \land (\forall A)
                                               • A \in \tau \Rightarrow \{x | x \in Space_T \ \sigma \land f \ x \in A\} \in \sigma\}
Hausdorff
                               \vdash Hausdorff
                                      = \{ \tau
                                      |\forall x y|
                                         • x \in Space_T \ \tau \land y \in Space_T \ \tau \land \neg x = y
                                               \Rightarrow (\exists A B)
                                               • A \in \tau
                                                     \land B \in \tau
                                                     \land x \in A
                                                     \land y \in B
                                                     \land A \cap B = \{\}\}
Compact
                               \vdash \forall \tau
```

```
\bullet \tau Compact
                                      = \{A
                                      |A \subseteq Space_T \tau
                                            \wedge (\forall V)
                                            \bullet \ V \subseteq \tau \, \wedge \, A \subseteq \bigcup \ V
                                                  \Rightarrow (\exists W \bullet W \subseteq V \land W \in Finite \land A \subseteq \bigcup W))
Connected
                             \vdash \forall \tau
                                \bullet \tau Connected
                                      = \{A
                                      |A \subseteq Space_T \tau
                                            \land (\forall B C)
                                            • B \in \tau \land C \in \tau \land A \subseteq B \cup C \land A \cap B \cap C = \{\}
                                                  \Rightarrow A \subseteq B \lor A \subseteq C
Homeomorphism
                             \vdash \forall \ \sigma \ \tau
                                • (\sigma, \tau) Homeomorphism
                                      = \{f
                                      |f \in (\sigma, \tau)| Continuous
                                            \wedge (\exists g
                                            • g \in (\tau, \sigma) Continuous
                                                  \wedge \ (\forall \ x \bullet \ x \in Space_T \ \sigma \Rightarrow g \ (f \ x) = x)
                                                  \land (\forall y \bullet y \in Space_T \ \tau \Rightarrow f \ (g \ y) = y))\}
Interior
Boundary
                             \vdash \ \forall \ \tau \ A
Closure
                                • \tau Interior A = \{x | \exists B \bullet B \in \tau \land x \in B \land B \subseteq A\}
                                      \wedge \tau \ Boundary \ A
                                         = \{x
                                         |x \in Space_T \tau
                                               \wedge (\forall B)
                                               • B \in \tau \land x \in B
                                                     \Rightarrow \neg B \cap A = \{\} \land \neg B \setminus A = \{\}\}
                                      \wedge \tau Closure A
                                         = \bigcap \{B | B \in \tau \ Closed \land A \cap Space_T \ \tau \subseteq B\}
Discrete_T
                             \vdash Discrete_T = \{\tau | \forall A \bullet A \subseteq Space_T \ \tau \Rightarrow A \in \tau\}
Covering Projection
                             \vdash \forall \sigma \tau
                                • (\sigma, \tau) CoveringProjection
                                      = \{p
                                      |p \in (\sigma, \tau)| Continuous
                                            \wedge (\forall y)
                                            • y \in Space_T \tau
                                                  \Rightarrow (\exists C
                                                  • y \in C
                                                        \land C \in \tau
                                                        \wedge (\exists U
                                                        • U \subseteq \sigma
                                                              \wedge (\forall x)
                                                              • x \in Space_T \ \sigma \land p \ x \in C
                                                                    \Rightarrow (\exists A \bullet x \in A \land A \in U))
                                                              \land (\forall A B)
```

```
\bullet \ A \in U \land B \in U \land \neg \ A \cap B = \{\}
                                                                  \Rightarrow A = B)
                                                            \land (\forall A)
                                                            \bullet A \in U
                                                                  \Rightarrow p
                                                                     \in (A \triangleleft_T \sigma,
                                                                           C
                                                                                 \lhd_T \tau) \ Homeomorphism))))
UniqueLiftingProperty
                             \vdash \forall \rho \sigma \tau p
                                • (\rho, p, \sigma, \tau) \in UniqueLiftingProperty
                                     \Leftrightarrow (\forall f \ g \ a)
                                     • f \in (\rho, \sigma) Continuous
                                              \land g \in (\rho, \sigma) \ Continuous
                                              \land (\forall x \bullet x \in Space_T \rho \Rightarrow p(f x) = p(g x))
                                              \land a \in Space_T \rho
                                              \wedge g \ a = f \ a
                                           \Rightarrow (\forall x \bullet x \in Space_T \rho \Rightarrow g x = f x))
Space_{K}
                            \vdash \forall C \bullet Space_K C = \bigcup \{c | \exists m \bullet (c, m) \in C\}
Skeleton
                            \vdash \forall n \ C \bullet n \ Skeleton \ C = \bigcup \{c | \exists m \bullet m \le n \land (c, m) \in C\}
Protocomplex \vdash \forall C \tau
                                • C \in Protocomplex \ \tau
                                     \Leftrightarrow (\forall c \ m \bullet (c, m) \in C \Rightarrow c \in \tau \ Closed)
                                        \wedge (\forall x)
                                        • x \in Space_K C
                                              \Rightarrow (\exists_1 (c, m))
                                              \bullet (c, m) \in C
                                                    \land x \in (m \ Skeleton \ C \lhd_T \tau) \ Interior \ c))
                                        \wedge (\forall A)
                                        • A \subseteq Space_K C
                                                 \wedge \ (\forall \ c \ m \bullet \ (c, \ m) \in C \Rightarrow A \cap c \in \tau \ Closed)
                                              \Rightarrow A \in \tau \ Closed
                                        \wedge (\forall c m)
                                        \bullet (c, m) \in C
                                              \Rightarrow \{(d, n)\}
                                                 |(d, n) \in C \land n < m \land \neg c \cap d = \{\}\}
                                                 \in Finite)
```

A.6 Theorems

```
enum\_set\_\subseteq\_thm \\ \vdash \forall \ A \ B \ C \bullet \ Insert \ A \ B \subseteq C \Leftrightarrow A \in C \land B \subseteq C \\ \cup\_enum\_set\_clauses \\ \vdash \bigcup \ \{\} = \{\} \land (\forall \ A \ B \bullet \bigcup \ (Insert \ A \ B) = A \cup \bigcup \ B) \\ \cap\_enum\_set\_clauses \\ \vdash \bigcap \ \{\} = Universe \land (\forall \ A \ B \bullet \bigcap \ (Insert \ A \ B) = A \cap \bigcap \ B) \\ finite\_image\_thm \\ \vdash \forall \ f \ A \bullet \ A \in Finite \Rightarrow \{y | \exists \ x \bullet \ x \in A \land y = f \ x\} \in Finite \\ \subseteq\_size\_thm \quad \vdash \forall \ a \ b \bullet \ a \in Finite \land b \subseteq a \Rightarrow \# \ b \leq \# \ a \\ \subseteq\_size\_thm1 \quad \vdash \forall \ a \ b \bullet \ a \in Finite \land b \subseteq a \land \neg \ b = a \Rightarrow \# \ b < \# \ a \\ finite\_\subseteq\_well\_founded\_thm
```

```
\vdash \forall p \ a
                                  • a \in Finite \land p \ a
                                        \Rightarrow (\exists b \bullet b \subseteq a \land p b \land (\forall c \bullet c \subseteq b \land p c \Rightarrow c = b))
empty\_open\_thm
                               \vdash \forall \ \tau \bullet \ \tau \in Topology \Rightarrow \{\} \in \tau
space\_t\_open\_thm
                               \vdash \forall \ \tau \bullet \ \tau \in Topology \Rightarrow Space_T \ \tau \in \tau
empty\_closed\_thm
                               \vdash \forall \ \tau \bullet \ \tau \in Topology \Rightarrow \{\} \in \tau \ Closed
space\_t\_closed\_thm
                               \vdash \forall \ \tau \bullet \ \tau \in Topology \Rightarrow Space_T \ \tau \in \tau \ Closed
open\_open\_neighbourhood\_thm
                               \vdash \forall \ \tau \ A
                                  • \tau \in Topology
                                         \Rightarrow (A \in \tau)
                                            \Leftrightarrow (\forall x \bullet x \in A \Rightarrow (\exists B \bullet B \in \tau \land x \in B \land B \subseteq A)))
closed\_open\_neighbourhood\_thm
                               \vdash \forall \ \tau \ A
                                  \bullet \ \tau \in \mathit{Topology}
                                        \Rightarrow (A \in \tau \ Closed)
                                            \Leftrightarrow A \subseteq Space_T \tau
                                               \wedge (\forall x)
                                               • x \in Space_T \ \tau \land \neg \ x \in A
                                                     \Rightarrow (\exists B \bullet B \in \tau \land x \in B \land B \cap A = \{\}))
\in \_space\_t\_thm
                               \vdash \ \forall \ \tau \ \textit{x} \ \textit{A} \bullet \ \textit{x} \in \textit{A} \ \land \ \textit{A} \in \tau \Rightarrow \textit{x} \in \textit{Space}_{\textit{T}} \ \tau
\in_closed_\in_space_t_thm
                               \vdash \forall \ \tau \ x \ A \bullet \ x \in A \land A \in \tau \ Closed \Rightarrow x \in Space_T \ \tau
closed\_open\_complement\_thm
                               \vdash \forall \ \tau \ A
                                  • \tau \in Topology
                                        \Rightarrow (A \in \tau \ Closed)
                                           \Leftrightarrow A \subseteq Space_T \ \tau \land Space_T \ \tau \setminus A \in \tau
\cup-open_thm \vdash \forall \ \tau \ A \ B \bullet \ \tau \in Topology \land A \in \tau \land B \in \tau \Rightarrow A \cup B \in \tau
\bigcup_{-}open\_thm \qquad \vdash \forall \ \tau \ V \bullet \ \tau \in Topology \ \land \ V \subseteq \tau \Rightarrow \bigcup \ V \in \tau
\cap_open_thm \vdash \forall \ \tau \ A \ B \bullet \ \tau \in Topology \land A \in \tau \land B \in \tau \Rightarrow A \cap B \in \tau
                              \vdash \forall \ \tau \ V
\bigcap-open_thm
                                  • \tau \in Topology \land \neg V = \{\} \land V \in Finite \land V \subseteq \tau
                                        \Rightarrow \bigcap V \in \tau
\cap_closed_thm \vdash \forall \tau A B
                                  • \tau \in Topology \land A \in \tau \ Closed \land B \in \tau \ Closed
                                         \Rightarrow A \cap B \in \tau \ Closed
\bigcap_closed_thm \vdash \forall \ \tau \ V
                                  • \tau \in Topology \land \neg V = \{\} \land V \subseteq \tau \ Closed
                                        \Rightarrow \cap V \in \tau \ Closed
\cup_closed_thm \vdash \forall \ \tau \ A \ B
                                  • \tau \in Topology \land A \in \tau \ Closed \land B \in \tau \ Closed
                                        \Rightarrow A \cup B \in \tau \ Closed
\bigcup_{closed\_thm} \vdash \forall \ \tau \ V
                                  • \tau \in Topology \land \neg V = \{\} \land V \in Finite \land V \subseteq \tau \ Closed
                                        \Rightarrow \bigcup V \in \tau \ Closed
```

 $finite_\cap_open_thm$

$$\vdash \forall \ \tau \ V$$

•
$$\tau \in Topology \land V \subseteq \tau \land \neg V = \{\} \land V \in Finite \Rightarrow \bigcap V \in \tau$$

 $subspace_topology_thm$

$$\vdash \forall \ \tau \ X \bullet \ \tau \in Topology \Rightarrow X \lhd_T \ \tau \in Topology$$

 $subspace_topology_space_t_thm$

$$\vdash \forall \tau A$$

• $\tau \in Topology \Rightarrow Space_T (A \triangleleft_T \tau) = A \cap Space_T \tau$

 $subspace_topology_space_t_thm1$

$$\vdash \forall \tau A$$

•
$$\tau \in Topology \land A \subseteq Space_T \ \tau$$

 $\Rightarrow Space_T \ (A \lhd_T \ \tau) = A$

 $universe_subspace_topology_thm$

$$\vdash \forall \ \tau \bullet \ Universe \ \lhd_T \ \tau = \tau$$

 $open_\subseteq_space_t_thm$

$$\vdash \forall \ \tau \ A \bullet \ \tau \in Topology \land A \in \tau \Rightarrow A \subseteq Space_T \ \tau$$

 $subspace_topology_space_t_thm2$

$$\vdash \forall \ \tau \ A \bullet \ \tau \in \mathit{Topology} \ \land \ A \in \tau \Rightarrow \mathit{Space}_T \ (A \lhd_T \tau) = A$$

 $subspace_topology_space_t_thm3$

$$\vdash \forall \ \tau \ A$$

•
$$\tau \in Topology \land A \in \tau \ Closed \Rightarrow Space_T \ (A \lhd_T \tau) = A$$

 $subspace_topology_closed_thm$

$$\vdash \ \forall \ X \ \tau$$

 $trivial_subspace_topology_thm$

$$\vdash \forall \ \tau \bullet \ \tau \in Topology \Rightarrow Space_T \ \tau \lhd_T \ \tau = \tau$$

 \subseteq $subspace_topology_thm$

$$\vdash \forall \ \tau \ A \ B \bullet \ A \subseteq B \Rightarrow A \vartriangleleft_T \ B \vartriangleleft_T \ \tau = A \vartriangleleft_T \ \tau$$

 $product_topology_thm$

$$\vdash \forall \sigma \tau$$

•
$$\sigma \in Topology \land \tau \in Topology \Rightarrow \sigma \times_T \tau \in Topology$$

 $product_topology_space_t_thm$

$$\vdash \forall \sigma \tau$$

•
$$\sigma \in Topology \land \tau \in Topology$$

 $\Rightarrow Space_T (\sigma \times_T \tau) = (Space_T \sigma \times Space_T \tau)$

 $subspace_product_subspace_thm$

$$\vdash \forall \sigma \tau X Y$$

•
$$\sigma \in Topology \land \tau \in Topology$$

 $\Rightarrow (X \lhd_T \sigma) \times_T (Y \lhd_T \tau) = (X \times Y) \lhd_T \sigma \times_T \tau$

 $unit_topology_thm$

$$\vdash 1_T \in Topology$$

 $space_t_unit_topology_thm$

$$\vdash Space_T 1_T = Universe$$

 $power_topology_length_thm$

$$\vdash \forall \tau \ n \ v \bullet v \in Space_T (\Pi_T \ n \ \tau) \Rightarrow \# \ v = n$$

 $power_topology_thm$

$$\vdash \forall \ \tau \ n \bullet \ \tau \in Topology \Rightarrow \Pi_T \ n \ \tau \in Topology$$

 $continuous_{\in_space_t_thm}$

```
\vdash \forall \sigma \tau f x
                               • f \in (\sigma, \tau) Continuous \land x \in Space_T \sigma
                                     \Rightarrow f \ x \in Space_T \ \tau
continuous\_open\_thm
                            \vdash \forall \sigma \tau f A
                               • f \in (\sigma, \tau) Continuous \land A \in \tau
                                    \Rightarrow \{x | x \in Space_T \ \sigma \land f \ x \in A\} \in \sigma
continuous\_closed\_thm
                            \vdash \forall \sigma \tau
                               • (\sigma, \tau) Continuous
                                    = \{f
                                    |(\forall x \bullet x \in Space_T \sigma \Rightarrow f x \in Space_T \tau)|
                                          \wedge (\forall A)
                                          • A \in \tau Closed
                                                \Rightarrow \{x | x \in Space_T \ \sigma \land f \ x \in A\}
                                                  \in \sigma \ Closed)
subspace\_continuous\_thm
                            \vdash \forall \sigma \tau A B f
                               • \sigma \in Topology
                                       \wedge \tau \in Topology
                                       \land f \in (\sigma, \tau) \ Continuous
                                       \wedge \ (\forall \ x \bullet \ x \in A \Rightarrow f \ x \in B)
                                    \Rightarrow f \in (A \triangleleft_T \sigma, B \triangleleft_T \tau) \ Continuous
subspace\_domain\_continuous\_thm
                            \vdash \forall \sigma \tau A B f
                              • \sigma \in Topology \land \tau \in Topology \land f \in (\sigma, \tau) Continuous
                                    \Rightarrow f \in (A \triangleleft_T \sigma, \tau) \ Continuous
empty\_continuous\_thm
                            \vdash \forall \sigma \tau f
                               • \sigma \in Topology \land \tau \in Topology
                                    \Rightarrow f \in (\{\} \lhd_T \sigma, \tau) \ Continuous
subspace\_range\_continuous\_thm
                            \vdash \forall \sigma \tau f B
                               • \sigma \in Topology
                                       \wedge \tau \in Topology
                                       \land f \in (\sigma, B \lhd_T \tau) \ Continuous
                                    \Rightarrow f \in (\sigma, \tau) \ Continuous
subspace\_range\_continuous\_\Leftrightarrow\_thm
                            \vdash \forall \sigma \tau f B
                               • \sigma \in Topology \land \tau \in Topology \land B \subseteq Space_T \tau
                                    \Rightarrow (f \in (\sigma, B \triangleleft_T \tau) Continuous
                                       \Leftrightarrow f \in (\sigma, \tau) \ Continuous
                                          \land \ (\forall \ x \bullet \ x \in Space_T \ \sigma \Rightarrow f \ x \in B))
subspace\_range\_continuous\_bc\_thm
                            \vdash \forall \sigma \tau f B
                               • \sigma \in Topology
                                       \wedge \tau \in Topology
                                       \land B \subseteq Space_T \tau
                                       \wedge \ (\forall \ x \bullet \ x \in Space_T \ \sigma \Rightarrow f \ x \in B)
                                       \land f \in (\sigma, \tau) \ Continuous
```

 $\Rightarrow f \in (\sigma, B \triangleleft_T \tau) \ Continuous$

$const_continuous_thm$

$$\vdash \forall \ \sigma \ \tau \ c$$

$$\bullet \ \sigma \in \ Topology \land \tau \in \ Topology \land c \in Space_T \ \tau$$

$$\Rightarrow (\lambda \ x \bullet c) \in (\sigma, \tau) \ Continuous$$

$id_continuous_thm$

 $\vdash \forall \ \tau \bullet \ \tau \in \textit{Topology} \Rightarrow (\lambda \ \textit{x} \bullet \ \textit{x}) \in (\tau, \ \tau) \ \textit{Continuous} \\ \textit{comp_continuous_thm}$

$_continuous_thm$

$left_proj_continuous_thm$

$$\vdash \forall \ \sigma \ \tau$$

$$\bullet \ \sigma \in Topology \land \tau \in Topology$$

$$\Rightarrow (\lambda \ (x, \ y) \bullet \ x) \in (\sigma \times_T \tau, \sigma) \ Continuous$$

$fst_continuous_thm$

$$\vdash \forall \ \sigma \ \tau$$

$$\bullet \ \sigma \in \ Topology \land \tau \in \ Topology$$

$$\Rightarrow Fst \in (\sigma \times_T \tau, \sigma) \ Continuous$$

$right_proj_continuous_thm$

$$\vdash \forall \ \sigma \ \tau$$

$$\bullet \ \sigma \in \ Topology \ \land \ \tau \in \ Topology$$

$$\Rightarrow (\lambda \ (x, \ y) \bullet \ y) \in (\sigma \times_T \ \tau, \ \tau) \ Continuous$$

$snd_continuous_thm$

$$\vdash \forall \ \sigma \ \tau$$

$$\bullet \ \sigma \in \ Topology \land \tau \in \ Topology$$

$$\Rightarrow Snd \in (\sigma \times_T \tau, \tau) \ Continuous$$

$product_continuous_thm$

$product_continuous_\Leftrightarrow_thm$

$$\vdash \forall f \ g \ \rho \ \sigma \ \tau$$

$$\bullet \ \rho \in Topology \land \sigma \in Topology \land \tau \in Topology$$

$$\Rightarrow ((\lambda \ z \bullet \ (f \ z, \ g \ z)) \in (\rho, \ \sigma \times_T \tau) \ Continuous$$

$$\Leftrightarrow f \in (\rho, \ \sigma) \ Continuous$$

```
 \land g \in (\rho, \tau) \ \textit{Continuous}) \\ \textbf{left\_product\_inj\_continuous\_thm} \\ \vdash \forall \ \sigma \ \tau \ y \\ \bullet \ \sigma \in \ \textit{Topology} \ \land \ \tau \in \ \textit{Topology} \ \land \ y \in \ \textit{Space}_T \ \tau \\ \Rightarrow (\lambda \ x \bullet \ (x, \ y)) \in (\sigma, \ \sigma \times_T \ \tau) \ \textit{Continuous} \\ \textbf{right\_product\_inj\_continuous\_thm}
```

 $\vdash \forall \sigma \tau x$

• $\sigma \in Topology \land \tau \in Topology \land x \in Space_T \sigma$ $\Rightarrow (\lambda \ y \bullet (x, \ y)) \in (\tau, \ \sigma \times_T \tau) \ Continuous$

 $range_unit_topology_continuous_thm$

 $\vdash \forall \ \tau \ f \bullet \ \tau \in \mathit{Topology} \Rightarrow f \in (\tau, \ 1_T) \ \mathit{Continuous}$

 $domain_unit_topology_continuous_thm$

 $diag_inj_continuous_thm$

$$\vdash \forall \ \tau$$

$$\bullet \ \tau \in Topology$$

$$\Rightarrow (\lambda \ x \bullet (x, \ x)) \in (\tau, \ \tau \times_T \tau) \ Continuous$$

 $cond_continuous_thm$

 $closed_\cup_closed_continuous_thm$

 $open_\cup_open_continuous_thm$

$$\vdash \forall \ \sigma \ \tau \ A \ B \ f \ g$$

$$\bullet \ \sigma \in Topology$$

$$\land \ \tau \in Topology$$

$$\land \ A \in \sigma$$

$$\land \ B \in \sigma$$

```
 \land f \in (A \lhd_T \sigma, \tau) \ Continuous \\ \land g \in (B \lhd_T \sigma, \tau) \ Continuous \\ \land (\forall x \bullet x \in A \cap B \Rightarrow f \ x = g \ x) \\ \Rightarrow (\lambda x \bullet if \ x \in A \ then \ f \ x \ else \ g \ x) \\ \in ((A \cup B) \lhd_T \sigma, \tau) \ Continuous
```

$compatible_family_continuous_thm$

$compatible_family_continuous_thm1$

$same_on_space_continuous_thm$

$same_on_space_continuous_thm1$

$$\vdash \forall \ \sigma \ \tau \ f \ g$$

$$\bullet \ \sigma \in Topology$$

$$\land \ \tau \in Topology$$

$$\land \ (\forall \ x \bullet \ x \in Space_T \ \sigma \Rightarrow f \ x = g \ x)$$

$$\Rightarrow (f \in (\sigma, \ \tau) \ Continuous \Leftrightarrow g \in (\sigma, \ \tau) \ Continuous)$$

$subspace_product_continuous_thm$

$$\vdash \forall \rho \ \sigma \ \tau \ f \ A \ B$$

$$\bullet \ \rho \in Topology$$

$$\land \ \sigma \in Topology$$

$$\land \ \tau \in Topology$$

$$\land \ \neg \ (A \times B) = \{\}$$

```
\land A \subseteq Space_T \rho
                                      \land B \subseteq Space_T \sigma
                                    \Rightarrow (f \in ((A \times B) \triangleleft_T \rho \times_T \sigma, \tau) \ Continuous
                                      \Leftrightarrow (\forall \ a \ b \bullet \ a \in A \land b \in B \Rightarrow f \ (a, \ b) \in Space_T \ \tau)
                                         \wedge (\forall a b E)
                                         • a \in A \land b \in B \land f(a, b) \in E \land E \in \tau
                                               \Rightarrow (\exists C D
                                               \bullet a \in C
                                                    \land C \in \rho
                                                    \wedge b \in D
                                                    \wedge D \in \sigma
                                                    \land (\forall x y)
                                                    • x \in A \cap C \land y \in B \cap D
                                                          \Rightarrow f(x, y) \in E)))
subspace\_topology\_hausdorff\_thm
                           \vdash \forall \tau X
                              • \tau \in Topology \land \tau \in Hausdorff \Rightarrow X \lhd_T \tau \in Hausdorff
product\_topology\_hausdorff\_thm
                           \vdash \forall \ \sigma \ \tau
                              • \sigma \in Topology
                                      \land \tau \in Topology
                                      \wedge \sigma \in Hausdorff
                                      \wedge \tau \in Hausdorff
                                    \Rightarrow \sigma \times_T \tau \in Hausdorff
punctured\_hausdorff\_thm
                           \vdash \forall \ \tau \ X \ x
                              • \tau \in Topology
                                      \wedge \tau \in Hausdorff
                                      \land X \subseteq Space_T \tau
                                      \land x \in Space_T \tau
                                   \Rightarrow X \setminus \{x\} \in X \triangleleft_T \tau
compact\_topological\_thm
                           \vdash \forall \ \tau \ X
                              • \tau \in Topology
                                    \Rightarrow (X \in \tau \ Compact \Leftrightarrow X \in (X \lhd_T \tau) \ Compact)
image\_compact\_thm
                           \vdash \forall f \ C \ \sigma \ \tau
                              • f \in (\sigma, \tau) Continuous
                                      \land C \in \sigma \ Compact
                                      \wedge \sigma \in Topology
                                      \land \tau \in Topology
                                   \Rightarrow \{y | \exists x \bullet x \in C \land y = f x\} \in \tau \ Compact
\cup_compact_thm
                           \vdash \forall C D \sigma
                              • C \in \sigma Compact \land D \in \sigma Compact \land \sigma \in Topology
                                    \Rightarrow C \cup D \in \sigma \ Compact
compact\_closed\_thm
                           \vdash \forall \tau \ C
                              \bullet \tau \in Topology \land \tau \in Hausdorff \land C \in \tau Compact
                                   \Rightarrow C \in \tau \ Closed
closed\_\subseteq\_compact\_thm
```

```
\vdash \forall \tau B C
                                 • \tau \in Topology
                                         \land \tau \in \mathit{Hausdorff}
                                         \land C \in \tau \ Compact
                                         \land B \in \tau \ Closed
                                         \wedge B \subseteq C
                                       \Rightarrow B \in \tau \ Compact
compact\_basis\_thm
                             \vdash \forall \ U \ \tau \ X
                                 • \tau \in Topology
                                         \wedge U \subseteq \tau
                                         \land (\forall A x)
                                         • x \in A \land A \in \tau \Rightarrow (\exists B \bullet x \in B \land B \subseteq A \land B \in U)
                                         \wedge X \subseteq Space_T \tau
                                         \wedge (\forall V)
                                         • V \subseteq U \wedge X \subseteq \bigcup V
                                               \Rightarrow (\exists \ W \bullet \ W \subseteq V \ \land \ W \in \mathit{Finite} \ \land \ X \subseteq (\ J \ W))
                                      \Rightarrow X \in \tau \ Compact
compact\_basis\_product\_topology\_thm
                             \vdash \forall \sigma \tau X
                                 • \sigma \in Topology
                                          \land \tau \in Topology
                                         \wedge X \subseteq Space_T (\sigma \times_T \tau)
                                         \wedge (\forall V)
                                         • V \subseteq \sigma \times_T \tau
                                                  \wedge (\forall D)
                                                  \bullet D \in V
                                                        \Rightarrow (\exists B C)
                                                        • B \in \sigma \land C \in \tau \land D = (B \times C))
                                                  \wedge X \subseteq \bigcup V
                                               \Rightarrow (\exists W \bullet W \subseteq V \land W \in Finite \land X \subseteq \bigcup W))
                                      \Rightarrow X \in (\sigma \times_T \tau) \ Compact
product\_compact\_thm
                             \vdash \forall X Y \sigma \tau
                                 • X \in \sigma Compact
                                         \land Y \in \tau \ Compact
                                         \wedge \sigma \in Topology
                                         \land \tau \in Topology
                                      \Rightarrow (X \times Y) \in (\sigma \times_T \tau) \ Compact
compact\_sequentially\_compact\_thm
                             \vdash \forall \ \tau \ X \ s
                                 • \tau \in Topology \land X \in \tau \ Compact \land (\forall \ m \bullet \ s \ m \in X)
                                      \Rightarrow (\exists x
                                      \bullet x \in X
                                            \wedge (\forall A)
                                            • A \in \tau \land x \in A
                                                  \Rightarrow (\forall m \bullet \exists n \bullet m \leq n \land s n \in A)))
connected\_topological\_thm
                             \vdash \forall \ \tau \ X
                                • \tau \in Topology
                                      \Rightarrow (X \in \tau \ Connected \Leftrightarrow X \in (X \lhd_T \tau) \ Connected)
```

$connected_closed_thm$

$$\vdash \ \forall \ \tau \ X$$

• τ Connected

$$= \{A \\ | A \subseteq Space_T \tau$$

 $\land \ (\forall \ B \ C$ $\bullet \ B \in \tau \ Closed$

$$\land \ C \in \tau \ Closed \\ \land \ A \subseteq B \cup C$$

$$\wedge A \cap B \cap C = \{\}$$

$$\Rightarrow A \subseteq B \lor A \subseteq C)$$

$connected_pointwise_thm$

$$\vdash \forall \ \tau \ X$$

 $\bullet \ \tau \in \mathit{Topology}$

$$\Rightarrow (X \in \tau \ Connected)$$

$$\Leftrightarrow (\forall x y)$$

$$\bullet \ x \in X \, \land \, y \in X$$

$$\Rightarrow (\exists Y$$

•
$$Y \subseteq X$$

$$\land x \in Y$$

$$\land y \in Y$$

 $\land Y \in \tau \ Connected)))$

$connected_pointwise_bc_thm$

$$\vdash \forall \ \tau \ X$$

•
$$\tau \in Topology$$

$$\wedge (\forall x y)$$

$$\bullet \ x \in X \land y \in X \\ \Rightarrow (\exists \ Y)$$

•
$$Y \subseteq X \land x \in Y \land y \in Y \land Y \in \tau \ \textit{Connected}))$$

 $\Rightarrow X \in \tau \ Connected$

$empty_connected_thm$

$$\vdash \forall \ \tau \bullet \ \tau \in Topology \Rightarrow \{\} \in \tau \ Connected$$

$singleton_connected_thm$

$$\vdash \forall \ \tau \ x$$

•
$$\tau \in Topology \land x \in Space_T \ \tau \Rightarrow \{x\} \in \tau \ Connected$$

$image_connected_thm$

$$\vdash \forall f \ X \ \sigma \ \tau$$

• $f \in (\sigma, \tau)$ Continuous

$$\land X \in \sigma \ Connected$$

$$\wedge \sigma \in Topology$$

$$\wedge \tau \in Topology$$

$$\Rightarrow \{y | \exists x \bullet x \in X \land y = f x\} \in \tau \ Connected$$

\cup _connected_thm

$$\vdash \forall C D \sigma$$

• $\sigma \in Topology$

$$\land C \in \sigma \ Connected$$

$$\land D \in \sigma \ Connected$$

$$\land \neg C \cap D = \{\}$$

$$\Rightarrow C \cup D \in \sigma \ Connected$$

$product_connected_thm$

$$\vdash \forall X Y \sigma \tau$$

•
$$X \in \sigma$$
 Connected $\land Y \in \tau$ Connected

 $\land \sigma \in \mathit{Topology}$

 $\land \tau \in \mathit{Topology}$

 $\Rightarrow (X \times Y) \in (\sigma \times_T \tau)$ Connected

$\cup _open_connected_thm$

$$\vdash \ \forall \ A \ B \ \sigma$$

• $A \in \sigma$

$$\land \neg A = \{\}$$

 $\land B \in \sigma$

 $\land \neg B = \{\}$

 $\land A \cup B \in \sigma \ Connected$

 $\Rightarrow \neg A \cap B = \{\}$

$\cup_{-} closed_connected_thm$

$$\vdash \forall A B \sigma$$

• $A \in \sigma$ Closed

$$\land \neg A = \{\}$$

 $\land B \in \sigma \ \mathit{Closed}$

$$\land \neg B = \{\}$$

 $\land A \cup B \in \sigma \ Connected$

$$\Rightarrow \neg A \cap B = \{\}$$

$\cup _ \cup _connected_thm$

$$\vdash \forall C D E \sigma$$

 $\bullet \ \sigma \in \ Topology$

 $\land C \in \sigma \ Connected$

 $\wedge D \in \sigma \ Connected$

 $\land E \in \sigma \ Connected$

$$\land \neg C \cap D = \{\}$$

$$\land \neg D \cap E = \{\}$$

 $\Rightarrow C \cup D \cup E \in \sigma \ Connected$

$cover_connected_thm$

$$\vdash \forall C U \sigma$$

 $\bullet \ \sigma \in \ Topology$

 $\land C \in \sigma \ Connected$

 $\land U \subseteq \sigma \ Connected$

 $\land C \subseteq \bigcup U$

 $\Rightarrow \bigcup \{D|D \in U \land \neg C \cap D = \{\}\} \in \sigma \ Connected$

$separation_thm$

$$\vdash \forall \tau \ C \ D$$

• $\tau \in Topology$

 $\land C \in \tau \ Connected$

 $\land \ D \in \tau \ \mathit{Connected}$

 $\land \neg C \cup D \in \tau \ Connected$

 $\Rightarrow (\exists A B)$

• $A \in \tau$

$$\land B \in \tau$$

$$\land (C \cup D) \cap A \cap B = \{\}$$

 $\land C \subseteq A$

 $\wedge D \subseteq B$

$finite_separation_thm$

$$\vdash \forall \tau \ U \ A$$

```
• \tau \in Topology
                                       \land \ U \in \mathit{Finite}
                                      \land \neg \{\} \in U
                                      \wedge U \subseteq \tau \ Connected
                                       \land A \in U
                                      \wedge (\forall B)
                                      • B \in U \land \neg A = B \Rightarrow \neg A \cup B \in \tau \ Connected)
                                    \Rightarrow (\exists C D)
                                    • C \in \tau
                                         \wedge D \in \tau
                                         \wedge A \subseteq C
                                         \wedge \bigcup (U \setminus \{A\}) \subseteq D
                                         \wedge \bigcup U \cap C \cap D = \{\})
connected\_extension\_thm
                           \vdash \forall \tau \ U \ B
                              • \tau \in Topology
                                       \land U \in Finite
                                      \land \neg \{\} \in U
                                      \land U \subseteq \tau \ Connected
                                      \land B \in \tau \ Connected
                                      \wedge \bigcup U \cup B \in \tau \ Connected
                                      \land \neg \bigcup U \subseteq B
                                    \Rightarrow (\exists A \bullet A \in U \land A \cup B \in \tau \ Connected \land \neg A \subseteq B)
connected\_chain\_thm
                           \vdash \forall \tau \ U \ A
                              • \tau \in Topology
                                      \land U \in Finite
                                      \land \neg \{\} \in U
                                       \land U \subseteq \tau \ Connected
                                      \wedge \bigcup U \in \tau \ Connected
                                      \land A \in U
                                    \Rightarrow (\exists L n
                                    \bullet L \theta = [A]
                                          \land (\forall m \bullet \bigcup (Elems (L m)) \in \tau \ Connected)
                                         \wedge (\forall m \bullet Elems (L m) \subseteq U)
                                         \wedge (\forall m)
                                         \bullet m < n
                                               \Rightarrow (\exists B)
                                               \bullet B \in U
                                                    \wedge \neg B \subseteq \bigcup (Elems (L m))
                                                    \wedge L(m+1) = Cons B(Lm))
                                         \wedge \bigcup U = \bigcup (Elems (L n))
                                          \wedge \ (\forall \ m \bullet \ L \ m \in Distinct))
connected\_triad\_thm
                           \vdash \forall \tau A B C
                              • \tau \in Topology
                                      \land A \in \tau \ Connected
                                      \land B \in \tau \ Connected
                                      \land C \in \tau \ Connected
                                      \land A \cup B \cup C \in \tau \ Connected
                                    \Rightarrow A \cup C \in \tau \ Connected \lor B \cup C \in \tau \ Connected
```

$connected_step_thm$

$id_homomorphism_thm$

$$\vdash \forall \ \tau \bullet \ \tau \in \textit{Topology} \Rightarrow (\lambda \ x \bullet \ x) \in (\tau, \ \tau) \ \textit{Homeomorphism comp_homeomorphism_thm}$$

$product_homeomorphism_thm$

$product_unit_homeomorphism_thm$

$$\begin{array}{l} \vdash \forall \ \tau \\ \bullet \ \tau \in \ Topology \\ \Rightarrow (\lambda \ x \bullet \ (x, \ One)) \in (\tau, \ \tau \times_T \ 1_T) \ Homeomorphism \end{array}$$

$swap_homeomorphism_thm$

$$\vdash \forall \ \sigma \ \tau$$

$$\bullet \ \sigma \in \ Topology \land \tau \in \ Topology$$

$$\Rightarrow (\lambda \ (x, \ y) \bullet \ (y, \ x))$$

$$\in (\sigma \times_T \tau, \ \tau \times_T \sigma) \ Homeomorphism$$

$homeomorphism_open_mapping_thm$

```
homeomorphism\_closed\_mapping\_thm
```

$homeomorphism_one_one_thm$

$homeomorphism_onto_thm$

$$\vdash \forall f \ \sigma \ \tau \ y$$

$$\bullet \ f \in (\sigma, \tau) \ Homeomorphism$$

$$\land \ \sigma \in Topology$$

$$\land \ \tau \in Topology$$

$$\land \ y \in Space_T \ \tau$$

$$\Rightarrow (\exists \ x \bullet \ x \in Space_T \ \sigma \ \land \ y = f \ x)$$

$homeomorphism_one_one_open_mapping_thm$

$homeomorphism_one_one_closed_mapping_thm$

$$\vdash \forall f \ \sigma \ \tau$$
• $\sigma \in Topology \land \tau \in Topology$

$$\Rightarrow (f \in (\sigma, \tau) \ Homeomorphism)$$

$$\Leftrightarrow (\forall x \ y)$$
• $x \in Space_T \ \sigma \land y \in Space_T \ \sigma \land f \ x = f \ y$

$$\Rightarrow x = y)$$

$$\land (\forall y)$$
• $y \in Space_T \ \tau$

$$\Rightarrow (\exists x \bullet x \in Space_T \ \sigma \land y = f \ x))$$

$$\land f \in (\sigma, \tau) \ Continuous$$

$$\land (\forall A)$$
• $A \in \sigma \ Closed$

$$\Rightarrow \{y | \exists x \bullet x \in A \land y = f \ x\} \in \tau \ Closed)$$

 $\subseteq_compact_homeomorphism_thm$

```
\vdash \forall f \sigma \tau B C
                                • \sigma \in Topology
                                        \land \sigma \in \mathit{Hausdorff}
                                        \land \tau \in Topology
                                        \wedge \tau \in \mathit{Hausdorff}
                                        \land C \in \sigma \ Compact
                                        \wedge B \subseteq C
                                        \land f \in (\sigma, \tau) \ Continuous
                                        \wedge (\forall x y \bullet x \in B \land y \in C \land f x = f y \Rightarrow x = y)
                                     \Rightarrow f
                                        \in (B \triangleleft_T \sigma,
                                              \{y | \exists x \bullet x \in B \land y = f x\}
                                                    \triangleleft_T \tau) Homeomorphism
interior\_boundary\_\subseteq\_space\_t\_thm
                            \vdash \forall \tau A
                                • \tau Interior A \subseteq Space_T \ \tau \land \tau \ Boundary \ A \subseteq Space_T \ \tau
interior\_\subseteq\_thm
                            \vdash \forall \ \tau \ A \bullet \ \tau \ Interior \ A \subseteq A
boundary\_interior\_thm
                            \vdash \forall \tau A
                                • \tau \in Topology
                                     \Rightarrow \tau \ Boundary \ A
                                        = Space_T \tau
                                           \setminus (\tau \ Interior \ A \cup \tau \ Interior \ (Space_T \ \tau \setminus A))
interior\_ \times \_thm
                            \vdash \forall \sigma \tau A B
                                • (\sigma \times_T \tau) Interior (A \times B)
                                     = (\sigma \ Interior \ A \times \tau \ Interior \ B)
open\_\Leftrightarrow\_disjoint\_boundary\_thm
                            \vdash \forall \ \tau \ A
                                • \tau \in Topology
                                     \Rightarrow (A \in \tau \Leftrightarrow A \subseteq Space_T \ \tau \land A \cap \tau \ Boundary \ A = \{\})
closed\_\Leftrightarrow\_boundary\_\subseteq\_thm
                            \vdash \forall \ \tau \ A
                                • \tau \in Topology
                                     \Rightarrow (A \in \tau \ Closed)
                                        \Leftrightarrow A \subseteq Space_T \ \tau \land \tau \ Boundary \ A \subseteq A)
interior\_\bigcup\_thm
                                • \tau \in Topology \Rightarrow \tau \ Interior \ A = \bigcup \{B | B \in \tau \land B \subseteq A\}
closure\_interior\_complement\_thm
                            \vdash \forall \ \tau \ A
                                • \tau \in Topology
                                     \Rightarrow \tau Closure A
                                        = Space_T \tau \setminus \tau \ Interior \ (Space_T \tau \setminus A)
open\_singletons\_discrete\_thm
                            \vdash \forall \tau
                                • \tau \in Topology
                                     \Rightarrow (\tau \in Discrete_T)
                                        \Leftrightarrow (\forall x \bullet x \in Space_T \tau \Rightarrow \{x\} \in \tau))
discrete\_t\_continuous\_thm
```

```
\vdash \forall \sigma \tau f
                              • \sigma \in Topology \land \tau \in Topology \land \sigma \in Discrete_T
                                    \Rightarrow (f \in (\sigma, \tau) \ Continuous)
                                       \Leftrightarrow (\forall x \bullet x \in Space_T \sigma \Rightarrow f x \in Space_T \tau))
connected\_discrete\_continuous\_thm
                           \vdash \forall \sigma \tau f
                               • \sigma \in Topology
                                       \land \tau \in Topology
                                       \land Space_T \sigma \in \sigma Connected
                                       \land \tau \in \mathit{Discrete}_T
                                       \land f \in (\sigma, \tau) \ Continuous
                                    \Rightarrow (\exists a \bullet \forall x \bullet x \in Space_T \sigma \Rightarrow f x = a)
covering\_projection\_continuous\_thm
                           \vdash \forall \sigma \tau p
                               • \sigma \in Topology
                                       \wedge \tau \in Topology
                                       \land \ p \in (\sigma, \ \tau) \ \textit{CoveringProjection}
                                    \Rightarrow p \in (\sigma, \tau) Continuous
unique\_lifting\_thm
                            \vdash \forall \rho \sigma \tau p
                               • \rho \in Topology
                                       \land \sigma \in Topology
                                       \wedge \tau \in Topology
                                       \land Space_T \rho \in \rho Connected
                                       \land p \in (\sigma, \tau) CoveringProjection
                                    \Rightarrow (\rho, p, \sigma, \tau) \in UniqueLiftingProperty
unique\_lifting\_bc\_thm
                            \vdash \forall \rho \sigma \tau p f g a
                               • \rho \in Topology
                                       \wedge \sigma \in Topology
                                       \land \tau \in \mathit{Topology}
                                       \land Space_T \rho \in \rho Connected
                                       \land p \in (\sigma, \tau) CoveringProjection
                                       \land f \in (\rho, \sigma) \ Continuous
                                       \land g \in (\rho, \sigma) \ Continuous
                                       \wedge \ (\forall \ x \bullet \ x \in Space_T \ \rho \Rightarrow p \ (f \ x) = p \ (g \ x))
                                       \land a \in Space_T \rho
                                       \wedge g \ a = f \ a
```

 \Rightarrow $(\forall x \bullet x \in Space_T \rho \Rightarrow g x = f x)$

THE THEORY metric_spaces \mathbf{B}

B.1 Parents

analysistopology trees

Children **B.2**

 $topology_{-}\mathbb{R}$

B.3 Constants

Metric $('a \times 'a \rightarrow \mathbb{R}) \mathbb{P}$ MetricTopology $('a \times 'a \rightarrow \mathbb{R}) \rightarrow 'a \mathbb{P} \mathbb{P}$ ListMetric $('a \times 'a \rightarrow \mathbb{R}) \rightarrow 'a \ LIST \times 'a \ LIST \rightarrow \mathbb{R}$

B.4 Fixity

Metric

Postfix 400: MetricTopology

Definitions B.5

 \vdash Metric $= \{D$ $|(\forall x y \bullet \theta. \le D(x, y))|$ $\wedge (\forall x y \bullet D (x, y) = \theta. \Leftrightarrow x = y)$ $\wedge (\forall x y \bullet D (x, y) = D (y, x))$ $\wedge (\forall x y z \bullet D (x, z) \leq D (x, y) + D (y, z))\}$ MetricTopology $\vdash \forall D$ • D Metric Topology $= \{A$ $|\forall x$ $\bullet x \in A$ • θ . $\langle e \land (\forall y \bullet D (x, y) < e \Rightarrow y \in A)) \}$ ListMetric $\vdash \forall D \ x \ v \ y \ w$ • $ListMetric\ D\ ([], []) = \theta.$

 $\wedge ListMetric D (Cons x v, [])$ = 1. + D(x, Arbitrary) + ListMetric D(v, []) $\land ListMetric D ([], Cons y w)$ = 1. + D (Arbitrary, y) + ListMetric D ([], w) $\land ListMetric \ D \ (Cons \ x \ v, \ Cons \ y \ w)$ = D(x, y) + ListMetric D(v, w)

B.6 Theorems

```
metric\_topology\_thm
                       \vdash \forall \ D \bullet \ D \in Metric \Rightarrow D \ Metric Topology \in Topology
space\_t\_metric\_topology\_thm
                       \vdash \forall D
                          • D \in Metric \Rightarrow Space_T (D MetricTopology) = Universe
open\_ball\_open\_thm
                       \vdash \forall D e x
                          • \theta. < e \land D \in Metric
                               \Rightarrow \{y|D(x, y) < e\} \in D MetricTopology
open\_ball\_neighbourhood\_thm
                       \vdash \forall D \ e \ x \bullet \ 0. < e \land D \in Metric \Rightarrow x \in \{y | D \ (x, y) < e\}
metric\_topology\_hausdorff\_thm
                       \vdash \forall \ D \bullet \ D \in Metric \Rightarrow D \ Metric Topology \in Hausdorff
product\_metric\_thm
                       \vdash \forall D1 D2
                          • D1 \in Metric \land D2 \in Metric
                              \Rightarrow (\lambda ((x1, x2), y1, y2))
                                 • D1(x1, y1) + D2(x2, y2)
                                 \in Metric
product\_metric\_topology\_thm
                       \vdash \forall D1 D2
                          \bullet D1 \in Metric \land D2 \in Metric
                               \Rightarrow (\lambda ((x1, x2), y1, y2))
                                   • D1(x1, y1) + D2(x2, y2)) Metric Topology
                                 = D1 MetricTopology \times_T D2 MetricTopology
lebesgue\_number\_thm
                       \vdash \forall D X U
                          • D \in Metric
                                 \land X \in D \ Metric Topology \ Compact
                                 \land U \subseteq D \ Metric Topology
                                 \wedge X \subseteq \bigcup U
                              \Rightarrow (\exists e
                               • \theta. < e
                                   \wedge (\forall x)
                                   \bullet x \in X
                                        \Rightarrow (\exists A)
                                        \bullet x \in A
                                            \land A \in U
                                            \land (\forall y \bullet D (x, y) < e \Rightarrow y \in A))))
collar\_thm
                       \vdash \forall D X U
                          • D \in Metric
                                 \land X \in D \ Metric Topology \ Compact
                                 \land A \in D \ Metric Topology
                                 \wedge X \subseteq A
                              \Rightarrow (\exists e
                              • \theta. < e
                                   \wedge (\forall x y)
                                   \bullet \ x \in X \ \land \ y \in Space_T \ \tau \ \land \ D \ (x, \ y) < e
                                        \Rightarrow y \in A)
```

 $list_metric_nonneg_thm$

$$\begin{array}{c} \vdash \forall \ D \ x \bullet \ D \in \mathit{Metric} \Rightarrow 0. \leq \mathit{ListMetric} \ D \ (x, \ y) \\ \textit{list_metric_sym_thm} \\ \vdash \forall \ D \ x \ y \\ \bullet \ D \in \mathit{Metric} \\ \Rightarrow \mathit{ListMetric} \ D \ (x, \ y) = \mathit{ListMetric} \ D \ (y, \ x) \\ \textit{list_metric_metric_thm} \end{array}$$

 $\vdash \ \, D \bullet \,\, D \in \, Metric \, \Rightarrow \, ListMetric \,\, D \in \, Metric$

C THE THEORY topology_ \mathbb{R}

C.1 Parents

 $metric_spaces$

C.2 Children

homotopy

C.3 Constants

 $egin{array}{lll} oldsymbol{D_R} & \mathbb{R} imes \mathbb{R} & \mathbb{R} \ oldsymbol{D_{R2}} & (\mathbb{R} imes \mathbb{R}) imes \mathbb{R} imes \mathbb{R} & \mathbb{R} imes \mathbb{R} \ \$ oldsymbol{Space} & \mathbb{N} o \mathbb{R} \ LIST \ \mathbb{P} \ \mathbb{P} \ \$ oldsymbol{SOpenCube} & \mathbb{N} o \mathbb{R} \ LIST \ \mathbb{P} \ \mathbb{P} \ \$ oldsymbol{Sphere} & \mathbb{N} o \mathbb{R} \ LIST \ \mathbb{P} \ \mathbb{P} \ \end{array}$

C.4 Aliases

 O_R $Open_R : \mathbb{R} \mathbb{P} \mathbb{P}$

C.5 Fixity

Postfix 400: Cube OpenCube Space Sphere

C.6 Definitions

$$\begin{array}{lll} \boldsymbol{D_R} & \vdash \forall \ x \ y \bullet \ D_R \ (x, \ y) = Abs \ (y - x) \\ \boldsymbol{D_{R2}} & \vdash \forall \ x1 \ y1 \ x2 \ y2 \\ & \bullet \ D_{R2} \ ((x1, \ y1), \ x2, \ y2) \\ & = Abs \ (x2 - x1) + Abs \ (y2 - y1) \\ \boldsymbol{Space} & \vdash \forall \ n \\ & \bullet \ n \ Space \\ & = \{v | \# \ v = n\} \ \lhd_T \ ListMetric \ D_R \ MetricTopology \\ \boldsymbol{Cube} & \vdash \forall \ n \\ & \bullet \ n \ Cube \\ & = \{v | Elems \ v \subseteq ClosedInterval \ 0. \ 1.\} \ \lhd_T \ n \ Space \\ \boldsymbol{OpenCube} & \vdash \forall \ n \\ & \bullet \ n \ OpenCube \\ & = \{v | Elems \ v \subseteq OpenInterval \ 0. \ 1.\} \ \lhd_T \ n \ Space \\ \boldsymbol{Sphere} & \vdash \forall \ n \\ & \bullet \ n \ Sphere = \{v | \neg \ Elems \ v \cap \{0.; \ 1.\} = \{\}\} \ \lhd_T \ n \ Cube \\ \end{array}$$

C.7 Theorems

 $connected _ \mathbb{R} _thm$

$$d.\mathbb{R}.2.def1 \qquad \vdash \forall \ xyf \ xy2 \\ \bullet \ D_{R2} \ (xyf, xy2) \\ = Abs \ (Fst \ xy2 - Fst \ xy1) \\ + Abs \ (Snd \ xy2 - Snd \ xy1)$$

$$open.\mathbb{R}.topology.thm \\ \vdash O_R \in Topology$$

$$space.t.\mathbb{R}.thm \\ \vdash Space_T \ O_R = Universe$$

$$closed.closed.\mathbb{R}.thm \\ \vdash O_R \ Closed = Closed_R$$

$$compact.compact.\mathbb{R}.thm \\ \vdash O_R \ Compact = Compact_R$$

$$open.\mathbb{R}.const.continuous.thm \\ \vdash V \sigma \ c \circ \sigma \in Topology \Rightarrow (\lambda \ x \circ \ c) \in (\sigma, O_R) \ Continuous$$

$$subspace.open.thm \\ \vdash \forall \tau \ A \\ \bullet \ \tau \in Topology \land A \in \tau \\ \Rightarrow (\forall B \circ B \in A \lhd_T \ \tau \Leftrightarrow B \in \tau \land B \subseteq A)$$

$$subspace.\mathbb{R}.open.thm \\ \vdash \forall A \land A \in O_R \Rightarrow (\forall B \circ B \in A \lhd_T \ O_R \Leftrightarrow B \in O_R \land B \subseteq A)$$

$$subspace.\mathbb{R}.open.thm \\ \vdash \forall A \land A \in O_R \Rightarrow (\forall B \circ B \in A \lhd_T \ O_R \Leftrightarrow B \in O_R \land B \subseteq A)$$

$$open.\mathbb{R}.sym.open.interval.th \\ \vdash \forall x \ y \ d \\ \Rightarrow (\exists \ d \ \circ \ \cdot < d \land OpenInterval \ (x - d) \ (x + d) \subseteq A))$$

$$\in .sym.open.interval.thm \\ \vdash \forall x \ y \ d \\ \Rightarrow x \in OpenInterval \ (y - d) \ (y + d) \Leftrightarrow Abs \ (x - y) < d$$

$$subspace.\mathbb{R}.space.\mathbb{L}.thm \\ \vdash \forall X \circ Space_T \ (X \lhd_T \ O_R) = X$$

$$subspace.\mathbb{R}.topology.thm \\ \vdash \forall X \circ Space_T \ (X \lhd_T \ O_R) = X$$

$$subspace.\mathbb{R}.topology.thm \\ \vdash \forall X \circ Space_T \ (X \lhd_T \ O_R) = X$$

$$subspace.\mathbb{R}.topology.thm \\ \vdash \forall X \circ Space_T \ (X \lhd_T \ O_R) = X$$

$$subspace.\mathbb{R}.topology.thm \\ \vdash \forall X \circ Space_T \ (X \lhd_T \ O_R) \ Continuous \\ cts.thm \\ \vdash \forall A \circ G \\ \Rightarrow (f \in (A \lhd_T \ O_R, O_R) \ Continuous \\ \Leftrightarrow (\forall x \circ x \in A \Rightarrow f \ Cls \ x))$$

$$continuous.cts.thm \\ \vdash \forall f \circ f \in (O_R, O_R) \ Continuous \\ \Leftrightarrow (\forall x \circ f \ Cls \ x) \Leftrightarrow f \ Cls \ x)$$

$$cts.at.\mathbb{R}.continuous.thm \\ \vdash \forall f \circ f \in (O_R, O_R) \ Continuous$$

$$universe.\mathbb{R}.continuous.thm \\ \vdash \forall f \circ f \ (x \circ f \ Cls \ x) \Leftrightarrow G \ Connected$$

$$closed.interval.connected.thm \\ \vdash \forall x \ y \circ x < y \Rightarrow ClosedInterval \ x \ y \in O_R \ Connected$$

```
\vdash \forall X
                              • X \in O_R Connected
                                   \Leftrightarrow (\forall x y z)
                                   • x \in X \land y \in X \land x \leq z \land z \leq y \Rightarrow z \in X)
\mathbb{R}_{-} \times_{-} \mathbb{R}_{-} topology\_thm
                           \vdash O_R \in Topology \Rightarrow O_R \times_T O_R \in Topology
continuous\_\mathbb{R}\_	imes\_\mathbb{R}_-\mathbb{R}_thm
                           \vdash \forall X f
                              • X \in O_R \times_T O_R
                                   \Rightarrow (f \in (X \triangleleft_T O_R \times_T O_R, O_R) Continuous
                                      \Leftrightarrow (\forall x y u v)
                                      • f(u, v) \in OpenInterval \ x \ y \land (u, v) \in X
                                            \Rightarrow (\exists a b c d
                                            • u \in OpenInterval \ a \ b
                                                 \land v \in OpenInterval \ c \ d
                                                 \wedge (\forall s t)
                                                 • s \in OpenInterval \ a \ b
                                                         \land t \in OpenInterval \ c \ d
                                                         \land (s, t) \in X
                                                      \Rightarrow f(s, t) \in OpenInterval(x, y)))
continuous\_\mathbb{R}\_\times \_\mathbb{R}_-\mathbb{R}\_thm1
                           \vdash \forall f
                              • f \in (O_R \times_T O_R, O_R) Continuous
                                   \Leftrightarrow (\forall x y u v)
                                   • f(u, v) \in OpenInterval \ x \ y
                                         \Rightarrow (\exists a b c d)
                                         \bullet u \in OpenInterval a b
                                              \land v \in OpenInterval \ c \ d
                                              \wedge (\forall s t)
                                              \bullet s \in OpenInterval a b
                                                      \land t \in OpenInterval \ c \ d
                                                    \Rightarrow f(s, t) \in OpenInterval(x, y))
continuous\_\mathbb{R}\_\times \_\mathbb{R}_-\mathbb{R}\_thm3
                           \vdash \forall X f
                              • X \in O_R \times_T O_R
                                   \Rightarrow (f \in (X \triangleleft_T O_R \times_T O_R, O_R) Continuous
                                      \Leftrightarrow (\forall e \ u \ v)
                                      • \theta. < e \land (u, v) \in X
                                            \Rightarrow (\exists d1 d2
                                            • 0. < d1
                                                 \wedge \theta . < d2
                                                 \land (\forall s t)
                                                 • Abs (s + \sim u) < d1
                                                         \wedge Abs (t + \sim v) < d2
                                                         \land (s, t) \in X
                                                      \Rightarrow Abs (f (s, t) + \sim (f (u, v)))
                                                         < e))))
continuous\_\mathbb{R}\_ \times \_\mathbb{R}_-\mathbb{R}\_thm4
                           \vdash \forall f
                              • f \in (O_R \times_T O_R, O_R) Continuous
```

$$\forall f$$

$$\bullet f \in (O_R \times_T O_R, O_R) \ Continuous$$

$$\Leftrightarrow (\forall e \ u \ v)$$

```
• \theta. < e
                                            \Rightarrow (\exists d1 d2
                                            • 0. < d1
                                                  \wedge \theta . < d2
                                                  \wedge (\forall s t)
                                                  • Abs\ (s + \sim u) < d1 \wedge Abs\ (t + \sim v) < d2
                                                        \Rightarrow Abs (f (s, t) + \sim (f (u, v)))
                                                           < e)))
plus\_continuous\_\mathbb{R}\_ \times \_\mathbb{R}\_thm
                             \vdash Uncurry \$+ \in (O_R \times_T O_R, O_R) Continuous
times\_continuous\_\mathbb{R}\_\times \_\mathbb{R}\_thm
                             \vdash Uncurry \$* \in (O_R \times_T O_R, O_R) Continuous
sqrt\_continuous\_thm
                             \vdash Sqrt \in (\{x | 0. \leq x\} \lhd_T O_R, O_R) \ Continuous
cond\_continuous\_\mathbb{R}\_thm
                             \vdash \forall b \ c \ f \ g \ \sigma \ \tau
                                 • \sigma \in Topology
                                         \wedge \tau \in Topology
                                         \land c \in (\sigma, O_R) Continuous
                                         \land f \in (\sigma, \tau) \ Continuous
                                         \land g \in (\sigma, \tau) \ Continuous
                                         \land (\forall x \bullet x \in Space_T \sigma \land c x = b \Rightarrow f x = g x)
                                      \Rightarrow (\lambda x \bullet if \ c \ x \leq b \ then f \ x \ else \ q \ x)
                                         \in (\sigma, \tau) Continuous
d_{-}\mathbb{R}_{-}metric_{-}thm
                             \vdash D_R \in Metric
d_{	ext{-}}\mathbb{R}_{	ext{-}}open_{	ext{-}}\mathbb{R}_{	ext{-}}thm
                             \vdash D_R \ Metric Topology = O_R
d_{-}\mathbb{R}_{-}2_{-}metric_{-}thm
                             \vdash D_{R2} \in Metric
d_{-}\mathbb{R}_{-}2_{-}open_{-}\mathbb{R}_{-}\times_{-}open_{-}\mathbb{R}_{-}thm
                             \vdash D_{R2} \ MetricTopology = O_R \times_T O_R
open \_ \mathbb{R}\_hausdorff\_thm
                             \vdash O_R \in \mathit{Hausdorff}
open {{}_{\scriptscriptstyle{-}}}\mathbb{R}{{}_{\scriptscriptstyle{-}}} \times {{}_{\scriptscriptstyle{-}}} open {{}_{\scriptscriptstyle{-}}}\mathbb{R}{{}_{\scriptscriptstyle{-}}} hausdorff {{}_{\scriptscriptstyle{-}}} thm
                             \vdash O_R \times_T O_R \in \mathit{Hausdorff}
\mathbb{R}\_lebesgue\_number\_thm
                             \vdash \forall X U
                                 • X \in Compact_R \land U \subseteq O_R \land X \subseteq \bigcup U
                                      \Rightarrow (\exists e)
                                      • \theta. < e
                                            \land (\forall x)
                                            \bullet x \in X
                                                  \Rightarrow (\exists A)
                                                  \bullet x \in A
                                                        \land A \in U
                                                        \land (\forall y \bullet Abs (y - x) < e \Rightarrow y \in A))))
closed\_interval\_lebesgue\_number\_thm
                             \vdash \forall y z U
```

• $U \subseteq O_R \wedge ClosedInterval \ y \ z \subseteq \bigcup \ U$

 $\Rightarrow (\exists e)$

```
• \theta. < e
                                            \land (\forall x)
                                            \bullet \ x \in ClosedInterval \ y \ z
                                                  \Rightarrow (\exists A)
                                                  \bullet x \in A
                                                       \land A \in U
                                                        \land (\forall y \bullet Abs (y - x) < e \Rightarrow y \in A))))
dissect\_unit\_interval\_thm
                             \vdash \forall x
                                 • \theta. < x
                                      \Rightarrow (\exists n t)
                                      \bullet 0 < n
                                            \wedge t \theta = \theta.
                                            \wedge t n = 1.
                                            \land (\forall i j \bullet i < j \Rightarrow t i < t j)
                                            \wedge (\forall i \bullet t (i + 1) - t i < x))
product\_interval\_cover\_thm1
                             \vdash \forall \tau \ U \ x
                                 • \tau \in Topology
                                         \wedge U \subseteq \tau \times_T O_R
                                         \land \ x \in \mathit{Space}_T \ \tau
                                         \land (\forall s)
                                         • s \in ClosedInterval \ 0. \ 1.
                                               \Rightarrow (\exists B \bullet (x, s) \in B \land B \in U))
                                      \Rightarrow (\exists n \ t \ A)
                                      • t \theta = \theta.
                                            \wedge t n = 1.
                                            \land (\forall i \bullet t i < t (i + 1))
                                            \land x \in A
                                            \land A \in \tau
                                            \wedge (\forall i
                                            \bullet i < n
                                                  \Rightarrow (\exists B)
                                                  \bullet B \in U
                                                        \wedge (A
                                                              \times ClosedInterval
                                                                 (t i)
                                                                 (t (i + 1))
                                                           \subseteq B)))
inc\_seq\_thm
                             \vdash \forall t i j
                                 • (\forall i \bullet t \ i < t \ (i + 1)) \Leftrightarrow (\forall i j \bullet i < j \Rightarrow t \ i < t \ j)
product\_interval\_cover\_thm
                             \vdash \forall \tau \ U \ x
                                 • \tau \in Topology
                                         \wedge U \subseteq \tau \times_T O_R
                                         \land x \in Space_T \tau
                                         \land (\forall s)
                                         • s \in ClosedInterval \ \theta. \ 1.
                                               \Rightarrow (\exists B \bullet (x, s) \in B \land B \in U))
                                      \Rightarrow (\exists n \ t \ A)
                                      • t \theta = \theta.
```

D THE THEORY homotopy

D.1 Parents

 $groups \ topology _ \mathbb{R}$

D.2 Constants

Paths $'a \mathbb{P} \mathbb{P} \to (\mathbb{R} \to 'a) \mathbb{P}$

\$PathConnected

$$'a \mathbb{P} \mathbb{P} \to 'a \mathbb{P} \mathbb{P}$$

Locally Path Connected

$$'a \mathbb{P} \mathbb{P} \mathbb{P}$$

\$Homotopy ' $a \mathbb{P} \mathbb{P} \times 'a \mathbb{P} \times 'b \mathbb{P} \mathbb{P} \rightarrow ('a \times \mathbb{R} \rightarrow 'b) \mathbb{P}$

 $\$ Homotopic \quad 'a \mathbb{P} \mathbb{P} \times 'a \mathbb{P} \times 'b \mathbb{P} \mathbb{P} \rightarrow ('a \rightarrow 'b) \rightarrow ('a \rightarrow 'b) \rightarrow BOOL$

 $\$+_{P}$ $(\mathbb{R} \to 'a) \to (\mathbb{R} \to 'a) \to \mathbb{R} \to 'a$

 $\mathbf{0}_{P} \qquad \qquad {'a} \to \mathbb{R} \to {'a}$

 \sim_{P} $(\mathbb{R} \to 'a) \to \mathbb{R} \to 'a$

PathHomotopic

$$'a \mathbb{P} \mathbb{P} \to (\mathbb{R} \to 'a) \to (\mathbb{R} \to 'a) \to BOOL$$

IotaI

$$\mathbb{R}\,\rightarrow\,\mathbb{R}$$

PathLiftingProperty

$$('a \rightarrow 'b) \leftrightarrow ('a \mathbb{P} \mathbb{P} \times 'b \mathbb{P} \mathbb{P})$$

Homotopy Lifting Property

$$'a \mathbb{P} \mathbb{P} \leftrightarrow (('b \rightarrow 'c) \times 'b \mathbb{P} \mathbb{P} \times 'c \mathbb{P} \mathbb{P})$$

Loops $'a \mathbb{P} \mathbb{P} \times 'a \to (\mathbb{R} \to 'a) \mathbb{P}$

FunGrpClass 'a $\mathbb{P} \ \mathbb{P} \times 'a \to (\mathbb{R} \to 'a) \to (\mathbb{R} \to 'a) \ \mathbb{P}$

 $FunGrpTimes 'a \mathbb{P} \mathbb{P} \times 'a \rightarrow (\mathbb{R} \rightarrow 'a) \mathbb{P} \rightarrow (\mathbb{R} \rightarrow 'a) \mathbb{P} \rightarrow (\mathbb{R} \rightarrow 'a) \mathbb{P}$

FunGrpUnit 'a $\mathbb{P} \mathbb{P} \times 'a \rightarrow (\mathbb{R} \rightarrow 'a) \mathbb{P}$

FunGrpInverse

$$'a \mathbb{P} \mathbb{P} \times 'a \to (\mathbb{R} \to 'a) \mathbb{P} \to (\mathbb{R} \to 'a) \mathbb{P}$$

FunGrp ' $a \mathbb{P} \mathbb{P} \times 'a \to (\mathbb{R} \to 'a) \mathbb{P} GROUP$

D.3 Fixity

Right Infix 300:

 $+_{P}$

Postfix 400: Homotopic Homotopy PathConnected

D.4 Definitions

Paths

PathConnected

• τ PathConnected

```
= \{A
                                    |A \subseteq Space_T \tau|
                                          \wedge (\forall x y)
                                          • x \in A \land y \in A
                                                \Rightarrow (\exists f
                                               • f \in Paths \ \tau
                                                     \land \ (\forall \ t \bullet f \ t \in A)
                                                     \wedge f \theta = x
                                                     \land f \ 1. = y)
Locally Path Connected \\
                            \vdash \forall \tau
                               \bullet \ \tau \in \mathit{LocallyPathConnected}
                                     \Leftrightarrow (\forall x A)
                                     • x \in A \land A \in \tau
                                          \Rightarrow (\exists B)
                                          • B \in \tau
                                               \land x \in B
                                               \wedge B \subseteq A
                                               \land B \in \tau \ PathConnected))
Homotopy
                            \vdash \forall \sigma X \tau
                               • (\sigma, X, \tau) Homotopy
                                    = \{H
                                    |H \in (\sigma \times_T O_R, \tau) Continuous
                                          \wedge \ (\forall \ x \ s \ t \bullet \ x \in X \Rightarrow H \ (x, \ s) = H \ (x, \ t))\}
Homotopic
                            \vdash \forall \sigma \ X \ \tau \ f \ g
                               • ((\sigma, X, \tau) \ Homotopic) \ f \ g
                                     \Leftrightarrow (\exists H
                                    • H \in (\sigma, X, \tau) \ Homotopy
                                          \wedge (\forall x \bullet H (x, \theta)) = f x
                                          \wedge (\forall x \bullet H(x, 1.) = g x))
                            \vdash \forall f g
+_P
                              \bullet f +_P g
                                    = (\lambda t)
                                    • if t \le 1 / 2
                                       then f(2.*t)
                                       else g(2.*(t - 1/2))
0_P
                            \vdash \forall x \bullet \theta_P x = (\lambda t \bullet x)
                            \vdash \forall f \bullet \sim_P f = (\lambda \ t \bullet f \ (1. - t))
PathHomotopic
                            \vdash \forall \ \tau \bullet \ PathHomotopic \ \tau = (O_R, \{0.; 1.\}, \tau) \ Homotopic
IotaI
                            \vdash IotaI
                                  = (\lambda x)
                                  • if x \leq 0, then 0, else if x \leq 1, then x else 1.)
PathLiftingProperty
                            \vdash \forall \sigma \tau p
                               • (p, \sigma, \tau) \in PathLiftingProperty
                                    \Leftrightarrow (\forall f \ y)
                                     • f \in Paths \ \tau \land y \in Space_T \ \sigma \land p \ y = f \ \theta.
                                          \Rightarrow (\exists q)
                                          • g \in Paths \ \sigma
                                               \wedge g \theta = y
```

```
\land (\forall s \bullet p (g s) = f s)))
Homotopy Lifting Property
                        \vdash \forall \rho \sigma \tau p
                           • (\rho, p, \sigma, \tau) \in HomotopyLiftingProperty
                                \Leftrightarrow (\forall f \ H)
                                • f \in (\rho, \sigma) Continuous
                                       \wedge H \in (\rho \times_T O_R, \tau) Continuous
                                       • x \in Space_T \ \rho \Rightarrow H \ (x, \ \theta.) = p \ (f \ x)
                                     \Rightarrow (\exists L
                                     • L \in (\rho \times_T O_R, \sigma) Continuous
                                          \land (\forall x \bullet x \in Space_T \rho \Rightarrow L(x, \theta) = f(x)
                                          \land (\forall x s)
                                          • x \in Space_T \rho
                                                 \land s \in ClosedInterval \ 0. \ 1.
                                               \Rightarrow p(L(x, s)) = H(x, s))
                        \vdash \forall \tau x
Loops
                           • Loops (\tau, x)
                                = Paths \ \tau \cap \{f | \forall \ t \bullet \ t \leq 0. \ \lor \ 1. \leq t \Rightarrow f \ t = x\}
FunGrpClass \vdash \forall \ \tau \ x \ f
                           • FunGrpClass\ (\tau,\ x)\ f
                                = EquivClass (Loops (\tau, x), PathHomotopic \tau) f
FunGrpTimes \vdash ConstSpec
                             (\lambda \ FunGrpTimes')
                                \bullet \ \forall \ \tau \ x \ p \ q \ f \ g
                                   • \tau \in Topology
                                          \land x \in Space_T \tau
                                         \land p \in Loops (\tau, x) / PathHomotopic \tau
                                         \land q \in Loops (\tau, x) / PathHomotopic \tau
                                         \wedge f \in p
                                          \land g \in q
                                       \Rightarrow FunGrpTimes'(\tau, x) p q
                                          = FunGrpClass (\tau, x) (f +_P g)
                              FunGrpTimes
FunGrpUnit \vdash \forall \ \tau \ x \bullet \ FunGrpUnit \ (\tau, \ x) = FunGrpClass \ (\tau, \ x) \ (\theta_P \ x)
FunGrpInverse
                        \vdash ConstSpec
                              (\lambda FunGrpInverse')
                                \bullet \ \forall \ \tau \ x \ p \ f
                                   • \tau \in Topology
                                          \land x \in Space_T \tau
                                          \land p \in Loops (\tau, x) / PathHomotopic \tau
                                         \land f \in p
                                       \Rightarrow FunGrpInverse'(\tau, x) p
                                          = FunGrpClass (\tau, x) (\sim_P f)
                              FunGrpInverse
                        \vdash \forall \tau x
FunGrp
                           • FunGrp(\tau, x)
                                = MkGROUP
                                  (Loops (\tau, x) / PathHomotopic \tau)
                                   (FunGrpTimes\ (\tau,\ x))
```

```
(FunGrpUnit (\tau, x))
(FunGrpInverse (\tau, x))
```

D.5 Theorems

 $path_connected_connected_thm$

$$\vdash \forall \ \tau \ X$$

$$\bullet \ \tau \in Topology \land X \in \tau \ PathConnected$$

$$\Rightarrow X \in \tau \ Connected$$

 $product_path_connected_thm$

 $homotopic_refl_thm$

$$\begin{array}{l} \vdash \forall \ \sigma \ X \ \tau \ f \\ \bullet \ \sigma \in \ Topology \ \land \ \tau \in \ Topology \\ \Rightarrow \ Reft \ ((\sigma, \ \tau) \ \ Continuous, \ (\sigma, \ X, \ \tau) \ \ Homotopic) \end{array}$$

 $homotopic_sym_thm$

 $homotopic_trans_thm$

$$\vdash \forall \ \sigma \ X \ \tau \ f \ g \ h$$

$$\bullet \ \sigma \in \ Topology \land \tau \in \ Topology$$

$$\Rightarrow \ Trans \ ((\sigma, \ \tau) \ Continuous, \ (\sigma, \ X, \ \tau) \ Homotopic)$$

 $homotopic_equiv_thm$

$$\vdash \forall \sigma \ X \ \tau \ f \ g \ h$$

$$\bullet \ \sigma \in Topology \land \tau \in Topology$$

$$\Rightarrow Equiv \ ((\sigma, \tau) \ Continuous, \ (\sigma, X, \tau) \ Homotopic)$$

 $homotopy_\subseteq_thm$

 $homotopic_\subseteq_thm$

 $homotopic_continuous_thm$

$$\vdash \forall \ \sigma \ \tau \ X \ f \ g$$

$$\bullet \ \sigma \in Topology$$

$$\land \ \tau \in Topology$$

$$\land \ ((\sigma, \ X, \ \tau) \ Homotopic) \ f \ g$$

```
\Rightarrow f \in (\sigma, \tau) \ Continuous \land g \in (\sigma, \tau) \ Continuous
homotopic\_comp\_left\_thm
                          \vdash \forall \rho \sigma \tau X f g h
                             • \rho \in Topology
                                     \land \sigma \in Topology
                                     \land \tau \in \mathit{Topology}
                                    \wedge ((\rho, X, \sigma) \ Homotopic) f q
                                     \land h \in (\sigma, \tau) \ Continuous
                                  \Rightarrow ((\rho, X, \tau) \ Homotopic)
                                     (\lambda x \bullet h (f x))
                                     (\lambda x \bullet h (q x))
homotopic\_comp\_right\_thm
                          \vdash \forall \rho \sigma \tau X f g h
                             • \rho \in Topology
                                     \land \sigma \in Topology
                                     \land \tau \in Topology
                                    \wedge ((\sigma, X, \tau) \ Homotopic) f g
                                    \wedge h \in (\rho, \sigma) Continuous
                                  \Rightarrow ((\rho, \{x | h \ x \in X\}, \tau) \ Homotopic)
                                    (\lambda x \bullet f (h x))
                                    (\lambda x \bullet g (h x))
homotopic \_ \mathbb{R} \_thm
                          \vdash \forall \tau f q
                             • \tau \in Topology
                                    \land f \in (\tau, O_R) \ Continuous
                                    \land g \in (\tau, O_R) \ \textit{Continuous}
                                  \Rightarrow ((\tau, \{x | g | x = f | x\}, O_R) | Homotopic) f g
half\_open\_interval\_retract\_thm
                          \vdash \forall b
                             • (\lambda \ s \bullet \ if \ s \le b \ then \ s \ else \ b)
                                  \in (O_R, \{s|s \leq b\} \triangleleft_T O_R) \ Continuous
closed\_interval\_retract\_thm
                          \vdash \forall a b
                             \bullet a \leq b
                                  \Rightarrow (\lambda \ s)
                                     • if s \le a then a else if s \le b then s else b)
                                     \in (O_R, ClosedInterval \ a \ b \lhd_T \ O_R) \ Continuous
\times\_closed\_interval\_retract\_thm
                          \vdash \forall \tau X \ a \ b
                             • \tau \in Topology \land X \subseteq Space_T \ \tau \land a \leq b
                                  \Rightarrow (\lambda (x, s))
                                     \bullet (x,
                                          (if \ s \leq a)
                                               then a
                                               else if s \leq b
                                               then s
                                               else \ b)))
                                     \in ((X \times Universe) \lhd_T \tau \times_T O_R,
                                          (X \times ClosedInterval \ a \ b)
                                               \lhd_T \tau \times_T O_R) Continuous
```

 $closed_interval_extension_thm$

```
\vdash \forall \rho \sigma f X a b
                             • \rho \in Topology
                                     \land \sigma \in Topology
                                     \land X \subseteq Space_T \rho
                                     \wedge a \leq b
                                     \wedge f
                                        \in ((X \times ClosedInterval \ a \ b) \triangleleft_T \rho \times_T O_R,
                                            \sigma) Continuous
                                  \Rightarrow (\exists g)
                                  • g
                                          \in ((X \times Universe) \lhd_T \rho \times_T O_R,
                                               \sigma) Continuous
                                       \land (\forall x s)
                                       • x \in X \land s \in ClosedInterval\ a\ b
                                             \Rightarrow g(x, s) = f(x, s)
\times_interval_glueing_thm
                          \vdash \forall \rho \sigma f g X a b
                             • \rho \in Topology
                                     \land \sigma \in Topology
                                     \wedge X \subseteq Space_T \rho
                                     \land a \leq b
                                     \wedge b \leq c
                                     \wedge f
                                       \in ((X \times ClosedInterval \ a \ b) \lhd_T \rho \times_T O_R,
                                            \sigma) Continuous
                                     \wedge g
                                        \in ((X \times ClosedInterval \ b \ c) \lhd_T \rho \times_T O_R,
                                            \sigma) Continuous
                                     \wedge \ (\forall \ x \bullet \ x \in X \Rightarrow f \ (x, \ b) = g \ (x, \ b))
                                  \Rightarrow (\exists h)
                                  • h
                                          \in ((X \times ClosedInterval \ a \ c) \lhd_T \rho \times_T O_R,
                                               \sigma) Continuous
                                       \wedge (\forall x s)
                                       • x \in X \land s \in ClosedInterval \ a \ b
                                            \Rightarrow h(x, s) = f(x, s)
                                       \land (\forall x s)
                                       \bullet \ x \in X \land s \in ClosedInterval \ b \ c
                                            \Rightarrow h(x, s) = g(x, s)
paths\_continuous\_thm
                             • \tau \in Topology \land f \in Paths \ \tau
                                  \Rightarrow f \in (O_R, \tau) \ Continuous
paths\_representative\_thm
                          \vdash \forall \tau f
                             • \tau \in Topology \land f \in (O_R, \tau) Continuous
                                  \Rightarrow (\exists_1 \ g)
                                  • q \in Paths \ \tau
                                       \land (\forall s)
                                       • s \in ClosedInterval \ 0. \ 1. \Rightarrow g \ s = f \ s))
path\_0\_path\_thm
```

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```
\vdash \forall \ \tau \ x \bullet \ \tau \in Topology \land x \in Space_T \ \tau \Rightarrow \theta_P \ x \in Paths \ \tau
path\_plus\_path\_path\_thm
                          \vdash \forall \tau f g
                             • \tau \in Topology
                                    \land f \in Paths \ \tau
                                    \land g \in Paths \ \tau
                                    \wedge g \ \theta . = f \ 1.
                                  \Rightarrow f +_P g \in Paths \tau
minus\_path\_path\_thm
                          \vdash \forall \ \tau \ f \bullet \ \tau \in Topology \land f \in Paths \ \tau \Rightarrow \sim_P f \in Paths \ \tau
path\_plus\_assoc\_thm
                          \vdash \forall \tau f g h
                             • \tau \in Topology
                                    \land f \in Paths \ \tau
                                    \land g \in Paths \ \tau
                                    \land h \in Paths \ \tau
                                    \wedge q \theta = f 1.
                                    \wedge h \theta = g 1.
                                  \Rightarrow PathHomotopic
                                    ((f +_P g) +_P h)
                                    (f +_P g +_P h)
path\_plus\_0\_thm
                          \vdash \forall \tau f x
                             • \tau \in Topology \land f \in Paths \ \tau \land f \ 1. = x
                                  \Rightarrow PathHomotopic \tau (f +_P \theta_P x) f
path\_0\_plus\_thm
                          \vdash \forall \tau f x
                             • \tau \in Topology \land f \in Paths \ \tau \land f \ \theta. = x
                                  \Rightarrow PathHomotopic \tau (\theta_P x +_P f) f
path\_plus\_minus\_thm
                          \vdash \forall \tau f x
                             • \tau \in Topology \land f \in Paths \ \tau \land f \ \theta. = x
                                  \Rightarrow PathHomotopic \tau (f +_P \sim_P f) (\theta_P x)
path\_minus\_minus\_thm
                          \vdash \forall f \bullet \sim_P (\sim_P f) = f
path\_minus\_plus\_thm
                          \vdash \forall \tau f x
                             • \tau \in Topology \land f \in Paths \ \tau \land f \ 1. = x
                                  \Rightarrow PathHomotopic \tau (\sim_P f +_P f) (\theta_P x)
paths\_space\_t\_thm
                          \vdash \forall \ \tau \ f \ x \bullet f \in Paths \ \tau \Rightarrow f \ x \in Space_T \ \tau
path\_comp\_continuous\_path\_thm
                          \vdash \forall \sigma \tau f g
                             • \sigma \in Topology
                                    \land \tau \in Topology
                                    \land f \in Paths \ \sigma
                                    \land q \in (\sigma, \tau) \ Continuous
                                  \Rightarrow (\lambda x \bullet g (f x)) \in Paths \tau
path\_from\_arc\_thm
```

 $\vdash \forall \tau f$

```
\bullet \tau \in Topology \land f \in (O_R, \tau) \ Continuous
                                 \Rightarrow (\lambda t)
                                   • if t \leq 0.
                                      then f 0.
                                      else if t \leq 1.
                                      then f t
                                      else f 1.)
                                   \in Paths \tau
loop\_from\_arc\_thm
                         \vdash \forall \tau f
                            • \tau \in Topology
                                   \land f \in (O_R, \tau) \ Continuous
                                   \wedge f 1. = f 0.
                                 \Rightarrow (\lambda t• if t \leq 0. \vee 1. \leq t then f 0. else f t)
                                   \in Loops (\tau, f \theta.)
open\_connected\_path\_connected\_thm
                         \vdash \forall \ \tau \ A
                            • \tau \in Topology
                                   \wedge \tau \in LocallyPathConnected
                                   \land A \in \tau
                                   \land A \in \tau \ Connected
                                 \Rightarrow A \in \tau \ PathConnected
open\_interval\_path\_connected\_thm
                         \vdash \forall \ x \ y \bullet \ OpenInterval \ x \ y \in O_R \ PathConnected
\mathbb{R}\_locally\_path\_connected\_thm
                         \vdash O_R \in LocallyPathConnected
product\_locally\_path\_connected\_thm
                         \vdash \forall \sigma \tau f \ a \ b \ c
                            • \sigma \in Topology
                                   \land \tau \in Topology
                                   \land \ \sigma \in \mathit{LocallyPathConnected}
                                   \land \tau \in LocallyPathConnected
                                 \Rightarrow \sigma \times_T \tau \in LocallyPathConnected
\in loops_thm
                       \vdash \forall \tau f x
                            • f \in Loops (\tau, x) \Leftrightarrow x = f \ \theta. \land f \in Loops (\tau, f \ \theta.)
loop\_path\_thm
                         \vdash \forall f \ \sigma \ x \bullet f \in Loops \ (\sigma, \ x) \Rightarrow f \in Paths \ \sigma
path\_0\_loop\_thm
                         \vdash \forall \tau x
                            • \tau \in Topology \land x \in Space_T \ \tau \Rightarrow \theta_P \ x \in Loops \ (\tau, x)
loop\_plus\_loop\_loop\_thm
                         \vdash \forall \tau \ x \ f \ g
                            • \tau \in Topology \land f \in Loops (\tau, x) \land g \in Loops (\tau, x)
                                 \Rightarrow f +_P g \in Loops (\tau, x)
minus\_loop\_loop\_thm
                         \vdash \forall \tau \ x \ f \ g
                            • \tau \in Topology \land f \in Loops (\tau, x)
                                 \Rightarrow \sim_P f \in Loops (\tau, x)
loop\_plus\_assoc\_thm
                         \vdash \forall \tau \ x \ f \ g \ h
                            • \tau \in Topology
```

```
\land f \in Loops (\tau, x)
                                 \land g \in Loops (\tau, x)
                                 \land h \in Loops (\tau, x)
                               \Rightarrow PathHomotopic
                                 ((f +_P g) +_P h)
                                 (f +_P q +_P h)
loop\_plus\_0\_thm
                        \vdash \forall \tau \ x \ f
                          • \tau \in Topology \land f \in Loops (\tau, x)
                               \Rightarrow PathHomotopic \tau (f +_P \theta_P x) f
loop\_0\_plus\_thm
                        \vdash \forall \tau f x
                          • \tau \in Topology \land f \in Loops (\tau, x)
                               \Rightarrow PathHomotopic \tau (\theta_P x +_P f) f
loop\_minus\_minus\_thm
                        \vdash \forall f \bullet \sim_P (\sim_P f) = f
loop\_plus\_minus\_thm
                        \vdash \forall \tau f x
                          • \tau \in Topology \land f \in Loops (\tau, x)
                               \Rightarrow PathHomotopic \tau (f +_P \sim_P f) (\theta_P x)
loop\_minus\_plus\_thm
                        \vdash \forall \tau f x
                          • \tau \in Topology \land f \in Loops (\tau, x)
                               \Rightarrow PathHomotopic \tau (\sim_P f +_P f) (\theta_P x)
loops\_homotopic\_equiv\_thm
                        \vdash \forall \tau x
                          • \tau \in Topology \land x \in Space_T \tau
                               \Rightarrow Equiv (Loops (\tau, x), PathHomotopic \tau)
loops\_homotopic\_refl\_thm
                        \vdash \forall \tau \ x \ p \ q
                          • \tau \in Topology \land x \in Space_T \ \tau \land f \in Loops \ (\tau, x)
                               \Rightarrow PathHomotopic \tau f f
loops\_homotopic\_sym\_thm
                        \vdash \forall \tau \ x \ p \ q
                          • \tau \in Topology
                                 \land x \in Space_T \tau
                                 \land f \in Loops (\tau, x)
                                 \land g \in Loops (\tau, x)
                                 \wedge PathHomotopic \tau f g
                               \Rightarrow PathHomotopic \tau q f
loops\_homotopic\_trans\_thm
                        \vdash \forall \tau \ x \ p \ q
                          • \tau \in Topology
                                 \land x \in Space_T \tau
                                 \land f \in Loops (\tau, x)
                                 \land g \in Loops (\tau, x)
                                 \land h \in Loops (\tau, x)
                                 \land PathHomotopic \tau f g
                                 \land PathHomotopic \tau g h
                               \Rightarrow PathHomotopic \tau f h
```

```
loop\_plus\_respects\_lemma1
                        \vdash \forall \tau \ x \ f \ g \ h
                          • \tau \in Topology
                                  \land x \in Space_T \tau
                                  \land f \in Loops (\tau, x)
                                 \land g \in Loops (\tau, x)
                                 \land h \in Loops (\tau, x)
                                 \land PathHomotopic \tau f g
                               \Rightarrow PathHomotopic \tau (f +_P h) (g +_P h)
loop\_plus\_respects\_lemma2
                        \vdash \forall \tau \ x \ f \ q \ h
                          • \tau \in Topology
                                  \land x \in Space_T \tau
                                 \land f \in Loops (\tau, x)
                                 \land g \in Loops (\tau, x)
                                 \land h \in Loops (\tau, x)
                                  \land PathHomotopic \tau g h
                               \Rightarrow PathHomotopic \tau (f +_P g) (f +_P h)
loop\_minus\_respects\_thm1
                        \vdash \forall \tau x
                          • \tau \in Topology \land x \in Space_T \tau
                               \Rightarrow (\forall g)
                               • q \in Loops (\tau, x)
                                    \Rightarrow ((\lambda \ f \bullet \ FunGrpClass \ (\tau, \ x) \ (f +_P \ g))
                                         Respects PathHomotopic \tau)
                                      (Loops (\tau, x))
loop\_minus\_respects\_thm2
                        \vdash \forall \tau x
                          • \tau \in Topology \land x \in Space_T \tau
                               \Rightarrow (\forall f)
                               • f \in Loops (\tau, x)
                                    \Rightarrow ((\lambda \ g \bullet \ FunGrpClass \ (\tau, \ x) \ (f +_P \ g))
                                         Respects PathHomotopic \tau)
                                      (Loops (\tau, x))
FunGrpTimes\_consistent
                        \vdash Consistent
                             (\lambda \ FunGrpTimes')
                               \bullet \ \forall \ \tau \ x \ p \ q \ f \ g
                                  • \tau \in Topology
                                        \land x \in Space_T \tau
                                        \land p \in Loops (\tau, x) / PathHomotopic \tau
                                        \land q \in Loops (\tau, x) / PathHomotopic \tau
                                        \land f \in p
                                        \land g \in q
                                      \Rightarrow FunGrpTimes'(\tau, x) p q
                                         = FunGrpClass (\tau, x) (f +_P g)
loop\_minus\_respects\_lemma
                        \vdash \forall \tau \ x \ f \ q
                          • \tau \in Topology
                                 \land x \in Space_T \tau
                                  \land f \in Loops (\tau, x)
```

```
\land g \in Loops (\tau, x)
                                  \land \ PathHomotopic \ \tau \ f \ g
                                \Rightarrow PathHomotopic \tau (\sim_P f) (\sim_P g)
loop\_minus\_respects\_thm
                        \vdash \forall \tau x
                           • \tau \in Topology \land x \in Space_T \tau
                                \Rightarrow ((\lambda \ f \bullet \ FunGrpClass \ (\tau, \ x) \ (\sim_P f))
                                     Respects PathHomotopic \tau)
                                  (Loops (\tau, x))
FunGrpInverse\_consistent
                        \vdash Consistent
                             (\lambda \ FunGrpInverse')
                                \bullet \ \forall \ \tau \ x \ p \ f
                                  • \tau \in Topology
                                         \land x \in Space_T \tau
                                         \land p \in Loops (\tau, x) / PathHomotopic \tau
                                         \land f \in p
                                       \Rightarrow FunGrpInverse'(\tau, x) p
                                         = FunGrpClass(\tau, x)(\sim_P f)
fun\_grp\_rep\_\exists\_thm
                        \vdash \forall \tau x
                           • \tau \in Topology
                                  \land x \in Space_T \tau
                                  \land \ p \in \mathit{Loops}\ (\tau,\ x)\ /\ \mathit{PathHomotopic}\ \tau
                                \Rightarrow (\exists f \bullet f \in Loops (\tau, x) \land f \in p)
fun\_grp\_class\_eq\_thm
                        \vdash \forall \tau x
                           • \tau \in Topology
                                  \land x \in Space_T \tau
                                  \land f \in Loops (\tau, x)
                                  \land g \in Loops (\tau, x)
                               \Rightarrow (FunGrpClass (\tau, x) f = FunGrpClass (\tau, x) g
                                  \Leftrightarrow PathHomotopic \ \tau \ f \ g
fun\_grp\_times\_\in\_car\_thm
                        \vdash \forall \tau \ x \ p \ q
                           • \tau \in Topology
                                  \land x \in Space_T \tau
                                  \land p \in Loops (\tau, x) / PathHomotopic \tau
                                  \land q \in Loops (\tau, x) / PathHomotopic \tau
                               \Rightarrow FunGrpTimes(\tau, x) p q
                                  \in Loops (\tau, x) / PathHomotopic \tau
fun\_grp\_unit\_\in\_car\_thm
                        \vdash \forall \tau x
                           • \tau \in Topology \land x \in Space_T \tau
                               \Rightarrow FunGrpUnit(\tau, x)
                                  \in Loops (\tau, x) / PathHomotopic \tau
fun\_grp\_inverse\_\in\_car\_thm
                        \vdash \forall \tau x p
                           • \tau \in Topology
                                  \land x \in Space_T \tau
                                  \land p \in Loops (\tau, x) / PathHomotopic \tau
```

```
\Rightarrow FunGrpInverse (\tau, x) p
                                   \in Loops (\tau, x) / PathHomotopic \tau
fun\_grp\_eq\_rep\_thm
                         \vdash \forall \tau \ x \ p \ f
                            • \tau \in Topology
                                   \land x \in Space_T \tau
                                   \land p \in Loops (\tau, x) / PathHomotopic \tau
                                   \land f \in p
                                \Rightarrow p = FunGrpClass(\tau, x) f
fun\_grp\_group\_thm
                           • \tau \in Topology \land x \in Space_T \tau
                                \Rightarrow FunGrp (\tau, x) \in Group
loop\_comp\_continuous\_loop\_thm
                         \vdash \forall \sigma \tau x f g
                           • \sigma \in Topology
                                   \land \tau \in Topology
                                   \land f \in Loops (\sigma, x)
                                   \land g \in (\sigma, \tau) \ Continuous
                                \Rightarrow (\lambda x \bullet g (f x)) \in Loops (\tau, g x)
iota\_i\_continuous\_thm
                         \vdash IotaI \in (O_R, O_R) \ Continuous
comp\_iota\_i\_path\_thm
                         \vdash \forall \sigma f
                           • \sigma \in Topology \land f \in (O_R, \sigma) Continuous
                                \Rightarrow (\lambda \ x \bullet f \ (IotaI \ x)) \in Paths \ \sigma
covering\_projection\_fibration\_thm
                         \vdash \forall \rho \sigma \tau p
                           • \rho \in Topology
                                   \wedge \sigma \in Topology
                                   \land \tau \in Topology
                                   \land p \in (\sigma, \tau) \ CoveringProjection
                                \Rightarrow (\rho, p, \sigma, \tau) \in HomotopyLiftingProperty
covering\_projection\_path\_lifting\_thm
                         \vdash \forall \sigma \tau p y f
                           • \sigma \in Topology
                                   \land \ \tau \in \ Topology
                                   \land p \in (\sigma, \tau) CoveringProjection
                                \Rightarrow (p, \sigma, \tau) \in PathLiftingProperty
covering\_projection\_path\_lifting\_bc\_thm
                         \vdash \forall \sigma \tau p y f
                           • \sigma \in Topology
                                   \land \tau \in Topology
                                   \land p \in (\sigma, \tau) CoveringProjection
                                   \land f \in Paths \ \tau
                                   \land y \in Space_T \sigma
                                   \wedge p y = f \theta.
                                \Rightarrow (\exists q)
                                • g \in Paths \ \sigma \land g \ \theta. = y \land (\forall \ s \bullet \ p \ (g \ s) = f \ s))
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